Matrix Scaling: A New Heuristic for the Feedback Vertex Set Problem

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- The order of a minimum FVS is denoted by $\tau(G)$.
- Minimizing τ(G) is NP-Hard [Karp, 1972].

Motivations

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• Finding feedback vertex sets in dependency digraphs can be used to resolve deadlock.

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- Selecting flip-flops in partial scan designs. It is a technique used in design for testing.

Three Main Steps

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Most FVS heuristics follow these steps.

 Digraph reductions: Removing vertices and arcs without changing the problem.

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- Digraph reductions: Removing vertices and arcs without changing the problem.
- **2** Vertex selection: Choose a vertex to be in a FVS.
- **3** Removing redundant vertices: The FVS may not be minimal.

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- O(|V| + |E|) running time

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- The operations can be done in any order [Levy and Low, 1988].

fvs_Max_Deg

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Choosing a vertex based off of vertex degrees is quicker.

```
Algorithm 1: MaxDeg
Data: A Digraph G = (X, U)
Result: A FVS S
begin
   S \leftarrow \emptyset
    LL_graph_reductions(G, S)
    L \leftarrow get\_SCC(G)
   while |L| \neq 0 do
       remove g from L
       v \leftarrow max(min(d^+(v), d^-(v))|v \in V(G))
       remove v from g
       S \leftarrow S + \{v\}
      LL_reductions(g, S)
       L \leftarrow get_SCC(g) + L
   end
   S \leftarrow remove\_redundant\_nodes(G, S)
   return S
end
```

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- They selected the vertex with the smallest mean return time.
- Their method operates in about $O(|F|n^{2.376})$ time.

MFVSmean

```
Algorithm 2: MFVSmean
Data: A Digraph G = (X, U)
Result: A EVS S
begin
    S \leftarrow \emptyset
    LL_graph_reductions(G, S)
    L \leftarrow get_SCC(G)
   while |L| \neq 0 do
       remove g from L
        v \leftarrow MFVSmean\_selection(g)
       remove v from g
       S \leftarrow S + \{v\}
       LL_reductions(g, S)
       L \leftarrow get_SCC(g) + L
    end
    S \leftarrow remove\_redundant\_nodes(G, S)
    return S
end
```

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MFVSmean

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Algorithm 3: MFVSmean_selection

Data: A Digraph G = (X, U)

Result: A vertex v

begin

end

$$\begin{array}{cccc}
\mathbf{P} &\leftarrow & CreateTransitionMatrix(G) \\
\pi' &\leftarrow & ComputeStationaryDistributionVector(\mathbf{P}) \\
\mathbf{P} &\leftarrow & CreateTransitionMatrix(G^{-1}) \\
\pi'' &\leftarrow & ComputeStationaryDistributionVector(\mathbf{P}) \\
\pi &\leftarrow & \pi' + \pi'' \\
determine \ v \in V \ \text{with} \ \pi_v = \|\pi\|_{\infty} \\
return \ v \\
\end{array}$$
end

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 $\frac{|DCU(G)|}{|S|}$ DCUs.

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• Finding all DCUs is hard.



Figure: For $t \ge 2$ the vertex z is not in a minimum FVS, but is in nearly every DCU and most cycles.

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Disjoint Cycle Unions and the Permanent

The permanent of a matrix **A** is defined as

$$perm(\mathbf{A}) = \sum_{\sigma} \prod_{i=1}^{n} a_{i,\sigma(i)}.$$

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The permanent of a matrix **A** is defined as

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The permanent counts the number of spanning disjoint cycle unions. We can create an auxilary digraph H from G by adding loops to the vertices of G.

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Disjoint Cycle Unions and the Permanent

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$$perm(\mathbf{A}) = \sum_{\sigma} \prod_{i=1}^{n} a_{i,\sigma(i)}.$$

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$$perm(\mathbf{A}(H)) - 1 = |DCU(G)|$$

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Let *H* be the auxilary digraph created as before. From *H* we can create a matrix called the m_{-} balance(**A**(H)) that gives the fraction of DCUs that every arc of *H* is in.

$$m_{-}bal(\mathbf{A}(H)) = \frac{a_{i,j} \times perm(\mathbf{A}(H)_{i,j})}{perm(\mathbf{A}(H))}.$$
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- The *m*_balance is doubly stochastic since every vertex is incident with every DCU.
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- The *m*_balance is very hard to calculate.

Sinkhorn Balancing.



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- Beichl and Sullivan [1999] showed that the limiting matrix of the Sinkhorn-Knopp algorithm can be used to estimate the permanent of **A**.
- We observed that we only need to complete log(n) iterations for the order to settle down.

fvs_sh_del

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```
Algorithm 7: FVS_SH_Del
Data: A Digraph G = (X, U)
Result: A EVS S
begin
   H \leftarrow G
   S \leftarrow \emptyset
   LL_graph_reductions(H, S)
    L \leftarrow get_SCC(H)
   while |L| \neq 0 do
       remove g from L
      v \leftarrow Sinkhorn\_selection(g)
      remove v from g
       S \leftarrow S + \{v\}
      LL_reductions(g, S)
       L \leftarrow get_SCC(g) + L
   end
    S \leftarrow remove_redundant_nodes(G, S)
   return S
end
```

 $O(|S|\log(n)n^2)$

fvs_sh_del_mod

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```
Algorithm 8: FVS_SH_DEL_MOD
Data: A Digraph G = (X, U)
Result: A EVS S
begin
    \begin{array}{c} H \longleftarrow G \\ S \longleftarrow \emptyset \end{array}
    LL_graph_reductions(H, S)
    while |V(H)| \neq 0 do
       v \leftarrow Sinkhorn\_selection(H)
       remove v from H
        S \leftarrow S + \{v\}
        LL_reductions(H, S)
    end
    S \leftarrow remove\_redundant\_nodes(G, S)
    return S
end
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- We then perform $k^2 n$ arc switches to simulate a uniformly chosen one.



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Erdos-Renyi Random Digraphs n = 100



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Erdos-Renyi Random Digraphs n = 500



Erdos-Renyi Random Digraphs n = 1000



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k-Regular Digraphs n = 100



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k-Regular Digraphs n = 1000



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Entropy

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$$entropy(\mathbf{A}) = -\sum_{i,j} a_{i,j} log(a_{i,j}).$$

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$$entropy(\mathbf{A}) = -\sum_{i,j} \mathsf{a}_{i,j} \mathsf{log}(\mathsf{a}_{i,j}).$$

Beichl and Sullivan showed the limiting matrix of the Sinkhorn-Knopp algorithm maximizes the entropy for all doubly-stochastic matrices with a given zero-one pattern.
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