

# A derivative-free algorithm resilient to straggler function evaluations

Clément W. Royer

Based on joint works with W. Hare, G. Jarry-Bolduc, S. Kerleau

Derivative-Free Optimization Symposium - Padova, June 24, 2024

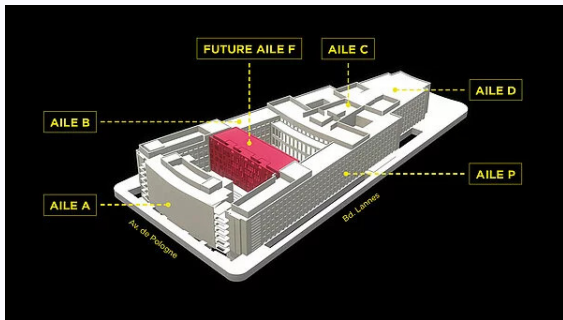
**Dauphine**  
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PaRis Artificial Intelligence Research InstitutE

  
FONDUS FRANCE CANADA POUR LA RECHERCHE  
FRANCE CANADA RESEARCH FUND

# Motivation: Dauphine's *Nouveau Campus*



- **New wing in construction** ⇒ 2024.
- Others renovated in order: B, P, C+D, A.
- Expected year of completion: 2027.

**Our task:** Allocate office space during the renovation process.

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## Our model for the Dauphine problem

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- $\sim 20$  hyperparameters defining the model.
- Parallel runs on the department server.

**Sub-task:** Optimize hyperparameters.

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## Problem challenges

- Cannot differentiate (easily) within Gurobi  
⇒ **Derivative-free algorithms!**
- Solving time depends on hyperparameters (3-48 hours for a feasible point!)  
⇒ **Limited benefits of parallelism.**

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**Can we cook up an algorithm adapted to this setting?**

- 1 Formal problem and algorithm
- 2 Building and using  $PkSS$
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- **Parallel evaluations of  $f$  allowed.**
- Evaluations can take unusually long  $\Rightarrow$  **Stragglers.**

# A (simplified) direct-search framework

**Inputs:**  $x_0 \in \mathbb{R}^n$ ,  $\alpha_0 > 0$ .

**Iteration  $i$ :** Given  $(x_i, \alpha_i)$ ,

- Choose a set  $\mathcal{D}_i \subset \mathbb{R}^n$  of  $m$  (nonzero) vectors.
- If  $\exists d_i \in \mathcal{D}_i$  such that

$$f(x_i + \alpha_i d_i) < f(x_i) - \alpha_i^2 \|d_i\|^2$$

set  $x_{i+1} := x_i + \alpha_i d_i$ ,  $\alpha_{i+1} := 2\alpha_i$ .

- Otherwise, set  $x_{i+1} := x_i$ ,  $\alpha_{i+1} := \alpha_i/2$ .

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- **Key:** Choice of  $\mathcal{D}_i$ .
- **Parallel version:** Works as long as all directions in  $\mathcal{D}_i$  have been polled when  $x_{i+1} = x_i$ .

## Usual tool: Positive spanning sets (PSS)

- $\mathcal{D} \subset \mathbb{R}^n$  PSS if it spans  $\mathbb{R}^n$  by **nonnegative linear combinations**  
 $\Rightarrow |\mathcal{D}| \geq n + 1$ .



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## Cosine measure

- For any  $\mathcal{D} \subset \mathbb{R}^n$ , the cosine measure of  $\mathcal{D}$  is

$$\text{cm}(\mathcal{D}) := \min_{v \neq 0} \max_{d \in \mathcal{D}} \frac{v^T d}{\|v\| \|d\|}.$$

- $\mathcal{D}$  PSS  $\iff \text{cm}(\mathcal{D}) > 0$ .

## Theorem: Complexity of direct search

Apply direct search with  $\mathcal{D}_i = \mathcal{D} \forall i$ ,  $\mathcal{D}$  PSS. Then the method satisfies

$$\min_{0 \leq i \leq J} \|\nabla f(x_i)\| \leq \epsilon$$

in at most

$$J = \mathcal{O}(|\mathcal{D}| \text{cm}(\mathcal{D})^{-2} \epsilon^{-2})$$

function evaluations.

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## Typical values

- $|\mathcal{D}| = \mathcal{O}(n)$ .
- $\text{cm}(\mathcal{D}) = \mathcal{O}(n^a)$ ,  $a \in \{-0.5, -1\}$ .

# Direct search and stragglers

**Inputs:**  $x_0 \in \mathbb{R}^n$ ,  $\alpha_0 > 0$ .

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- If  $\exists d_i \in \mathcal{D}_i \setminus \mathcal{S}_i$  such that

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**Straggler model:** At every iteration  $i$ ,

- $\exists \mathcal{S}_i \subset \mathcal{D}_i$  of **straggler directions** ( $f$  much longer to evaluate).
- $\mathcal{S}_i$  unknown before evaluations launched!
- Evaluations in  $\mathcal{S}_i$  cannot be used in analyzing the method.

## Positive $k$ -spanning sets (PkSS), $k \geq 1$

- $\mathcal{D} \subset \mathbb{R}^n$  PkSS if any  $\mathcal{N} \subset \mathcal{D}$  with  $|\mathcal{N}| = |\mathcal{D}| - k + 1$  is a PSS.

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- $\mathcal{D}$  **positive  $k$ -basis** if no proper subset of  $\mathcal{D}$  is a PkSS.



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- $\mathcal{D}$  positive  $k$ -basis if no proper subset of  $\mathcal{D}$  is a PkSS.
- Definition inherited from D. A. Marcus ('81, '84).
- $k = 1$ : PSS/Positive basis.
- $\mathcal{D}$  PkSS  $\Rightarrow |\mathcal{D}| \geq \max\{k, n + 2k - 1\}$ .

## The $k$ -cosine measure

- For any  $\mathcal{D} \subset \mathbb{R}^n$ , the  $k$ -cosine measure of  $\mathcal{D}$  is

$$\text{cm}_k(\mathcal{D}) := \min_{v \neq 0} \max_{\substack{\mathcal{N} \subset \mathcal{D} \\ |\mathcal{N}|=k}} \max_{d \in \mathcal{N}} \frac{v^T d}{\|v\| \|d\|}.$$

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## Properties

- Equivalent definition:

$$\text{cm}_k(\mathcal{D}) = \min_{\substack{\mathcal{N} \subset \mathcal{D} \\ |\mathcal{N}|=|\mathcal{D}|-k+1}} \text{cm}(\mathcal{N}).$$

- For any  $\mathcal{D}$  (not necessarily PkSS !),

$$\text{cm}(\mathcal{D}) \geq \dots \geq \text{cm}_{|\mathcal{D}|-1}(\mathcal{D}) \geq \text{cm}_{|\mathcal{D}|}(\mathcal{D}).$$

## Theorem

- Apply direct search with  $\mathcal{D}_i = \mathcal{D} \forall i$ ,  $\mathcal{D}$  PkSS.
- Suppose less than  $k$  stragglers per iteration:  $|\mathcal{S}_i| \leq k - 1 \forall i$ .

Then the method satisfies

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## Typical values?

- $|\mathcal{D}| \geq \mathcal{O}(n + k)$ .
- $\text{cm}_k(\mathcal{D}) = \mathcal{O}(?)$ .

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Our baseline: Maximal (coordinate) positive basis

- $\mathcal{D}_\oplus := \{e_1, \dots, e_n, -e_1, \dots, -e_n\}$ , with  $\{e_I\}_I$  coordinate basis vectors.
- $\beta\mathcal{D}_\oplus$ : multiply all vectors by real  $\beta$ .

# Produce PkSS in practice (1/2)

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First proposal: Duplicate vectors

Let  $\beta_1, \dots, \beta_k$  be  $k$  distinct positive real numbers. The set

$$\mathcal{D}_{\oplus}^{\beta_{1:k}} := \bigcup_{j=1}^k \beta_j \mathcal{D}_{\oplus}$$

is a PkSS with  $\text{cm}_k(\mathcal{D}_{\oplus}^{\beta_{1:k}}) = \text{cm}(\mathcal{D}_{\oplus}) = \frac{1}{\sqrt{n}}$ .



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- Easy construction, even yields a positive  $k$ -basis!
- Lacks diversity, redundancy if coupled with line search.

## Produce PKSS in practice (2/2)

Our baseline: Minimal (coordinate) positive basis

- $\mathcal{D}_{n+1} := \{e_1, \dots, e_n, -\sum_{l=1}^n e_l\}$ , with  $\{e_l\}$  coordinate basis vectors.
- $R\mathcal{D}_{n+1}$ : Apply **Rotation matrix**  $R \in \mathbb{R}^{n \times n}$  to all vectors.

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Let  $R_1, \dots, R_k$  be  $k$  distinct positive real numbers. The set

$$\mathcal{D}_{n+1}^{R_{1:k}} := \bigcup_{j=1}^k R_j \mathcal{D}_{n+1}$$

is a PkSS with  $\text{cm}_k(\mathcal{D}_{n+1}^{R_{1:k}}) \geq \text{cm}(\mathcal{D}_{n+1}) = \frac{1}{\sqrt{n^2 + 2(n-1)\sqrt{n}}}$ .

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*Includes:*

- Positive  $k$ -bases/PkSS with duplicates.
- PkSS with no duplicates but not positive  $k$ -bases.
- **Positive  $k$ -basis with no duplicates!**

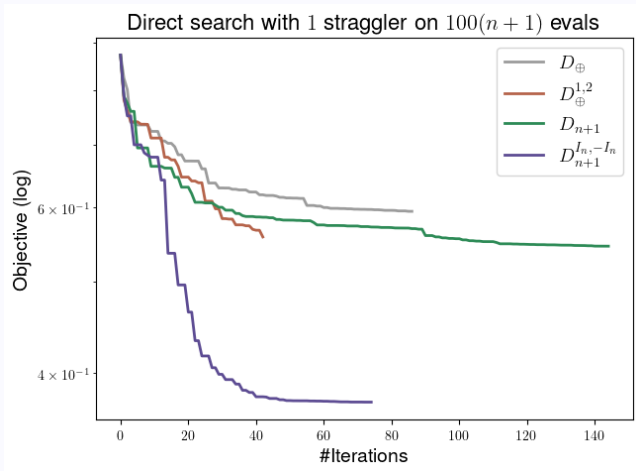
$$\underset{x \in \mathbb{R}^n}{\text{minimize}} \frac{1}{2n} \sum_{i=1}^{2n} \phi(a_i^T x - b_i), \quad \phi(t) = \frac{t^2}{1+t^2}.$$

- $a_i$  i.i.d Gaussian,  $b_i = a_i^T z + 3u_1 + u_2$ ,  $\{z, u_1\}$  Gaussian,  $u_2$  Bernoulli.

Comparison: Direct search with PSS/P2SS, **one straggler/iteration.**

$\mathcal{D}$	$ \mathcal{D} $	cm?
$\mathcal{D}_{\oplus}$	$2n$	cm = $\frac{1}{\sqrt{n}}$
$\mathcal{D}_{\oplus}^{1,2}$	$4n$	cm <sub>2</sub> = $\frac{1}{\sqrt{n}}$
$\mathcal{D}_{n+1}$	$n+1$	cm = $\frac{1}{\sqrt{n^2+2(n-1)\sqrt{n}}}$
$\mathcal{D}_{n+1}^{l_n, -l_n}$	$2n+2$	cm <sub>2</sub> = $\frac{1}{\sqrt{n^2+2(n-1)\sqrt{n}}}$ .

# Results in dimension 10



- P2SSs can outperform PSSs with stragglers!
- On 100 runs,  $\mathcal{D}_{n+1}^{I_n, -I_n}$  gives best results.

## DFO with stragglers

- Resilient notion of PSS.
- Convergent algorithm.
- Numerical proof of concept.

## References

- W. Hare, G. Jarry-Bolduc, S. Kerleau and C. W. Royer.  
**Using orthogonally structured positive bases for constructing positive  $k$ -spanning sets with cosine measure guarantees**,  
Lin. Alg. Appl. 680:183-207, 2024.
- S. Kerleau and C. W. Royer.  
**A derivative-free algorithm resilient to straggler function evaluations**,  
Working paper.

- About  $PkSS$ :
  - Upper bounds on the size of positive  $k$ -bases? (Nontrivial!)
  - Best  $PkSS$  in terms of  $\ell$ -cosine measure?
  - Connections to strongly connected graphs and neighborly polytopes (!)



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Grazie mille!

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