

EVALUATING AND TUNING
PRECISION AND RECALL FOR GENERATIVE MODELS
DATA SCIENCE LAB

Alexandre Vérine

Junior AI Fellow of University PSL,
Centre des Données, ENS-PSL

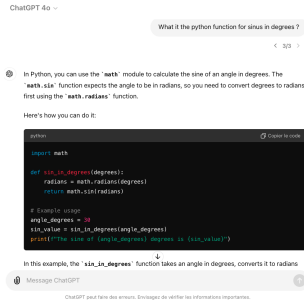
October 16, 2024

GENERATIVE MODELS

CONTEXT

In the past few years, generative models have made significant progress in various domains of application.

Text Generation



ChatGPT 4o

What is the python function for sinus in degrees?

In Python, you can use the `math` module to calculate the sine of an angle in degrees. The `math.sin` function expects the angle to be in radians, so you need to convert degrees to radians first using the `math.radians` function.

Here's how you can do it:

```
import math

def sin_in_degrees(degrees):
    radians = math.radians(degrees)
    return math.sin(radians)

# Example usage
angle_degrees = 30
sin_value = sin_in_degrees(angle_degrees)
print(f"The sine of {angle_degrees} degrees is {sin_value}")
```

In this example, the `sin_in_degrees` function takes an angle in degrees, converts it to radians

Message ChatGPT

ChatGPT peut faire des erreurs. Essayez de vérifier les informations importantes.

eg: Code Completion

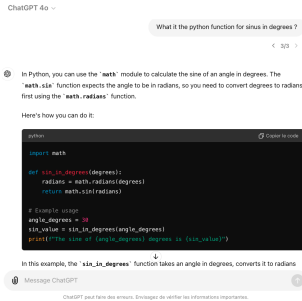
GENERATIVE MODELS

CONTEXT

In the past few years, generative models have made significant progress in various domains of application.

Text Generation

Image/Video Generation



eg: Code Completion

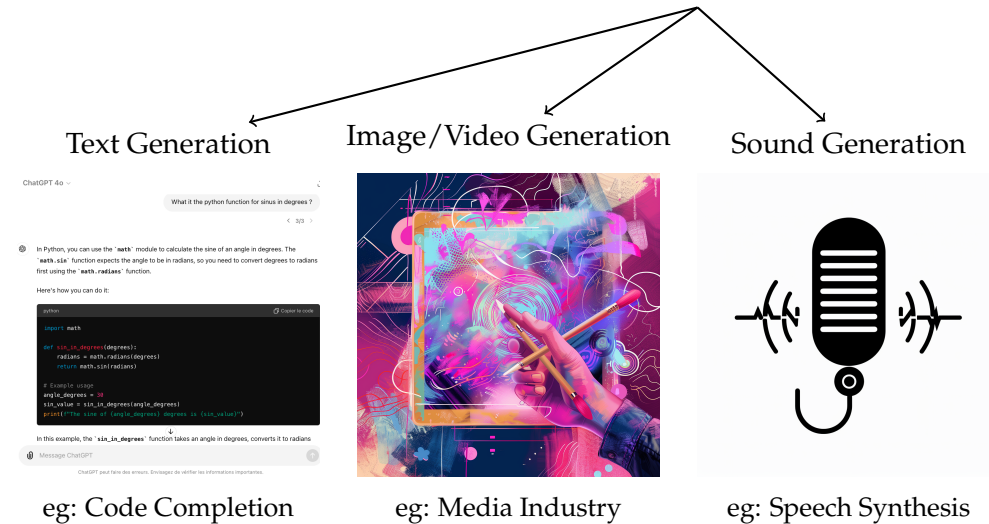


eg: Media Industry

GENERATIVE MODELS

CONTEXT

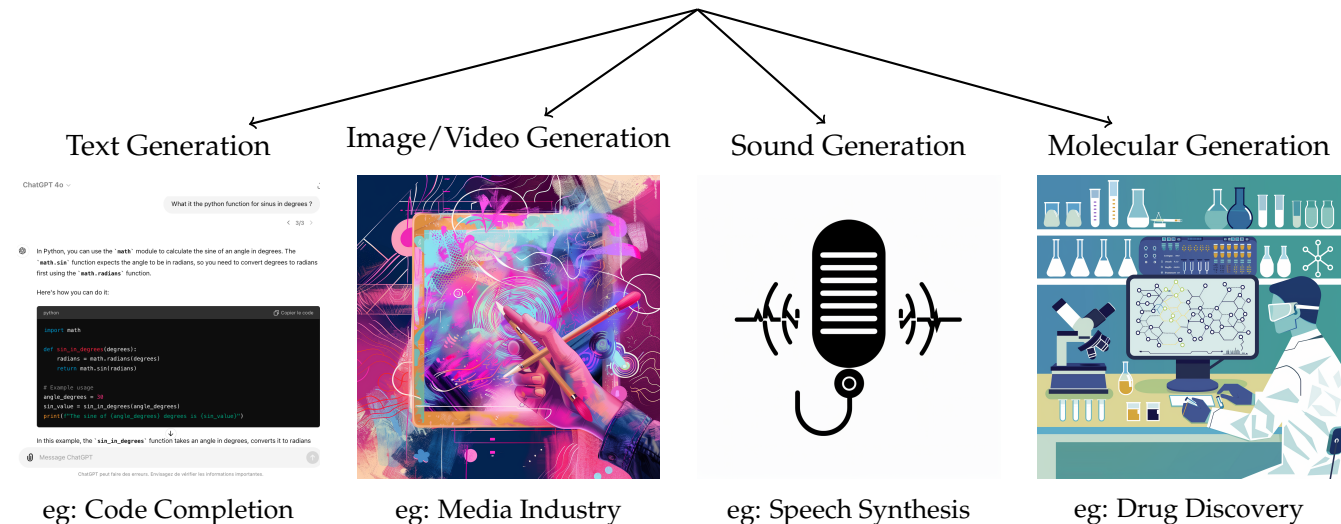
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GENERATIVE MODELS

CONTEXT

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THE VARIOUS PERFORMANCES OF GENERATIVE MODELS

MOTIVATION

As the generation becomes better, the evaluation becomes more challenging.

DALL·E 2 (2023)



Midjourney v5 (2023)



?

Prompt: *A dog playing with a child.*

THE VARIOUS PERFORMANCES OF GENERATIVE MODELS

MOTIVATION

As the generation becomes better, the evaluation becomes more challenging.

DALL·E 2 (2023)



Low Quality
High Diversity

Midjourney v5 (2023)



High Quality
Low Diversity

≠

Prompt: *A dog playing with a child.*

THE VARIOUS PERFORMANCES OF GENERATIVE MODELS

TRADITIONAL METRICS

Traditional metrics such as the **Fréchet Inception Distance (FID)** encapsulate both quality and diversity in an unclear way:

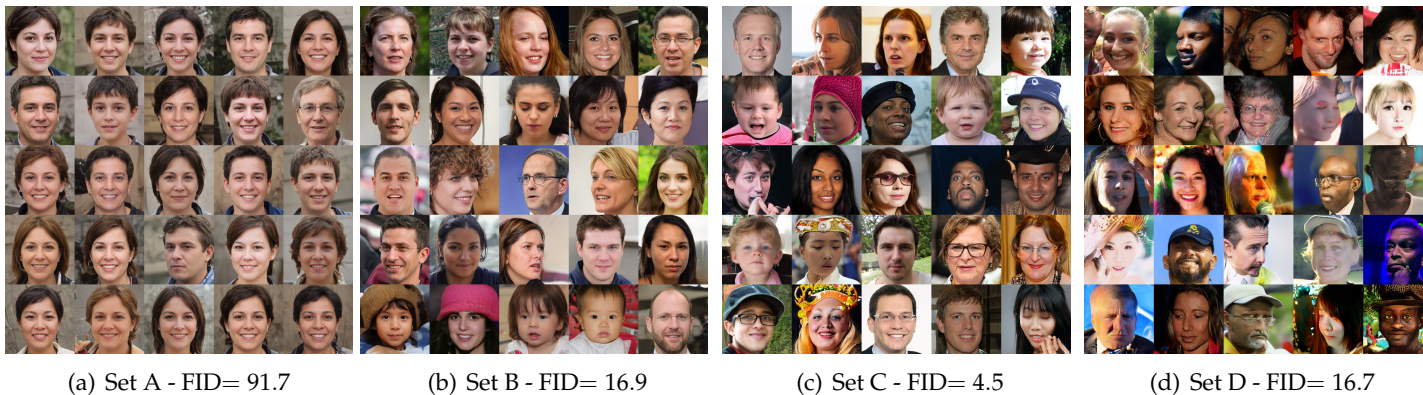


Figure. Source: Kynkäänniemi et al. [15]

OUTLINE

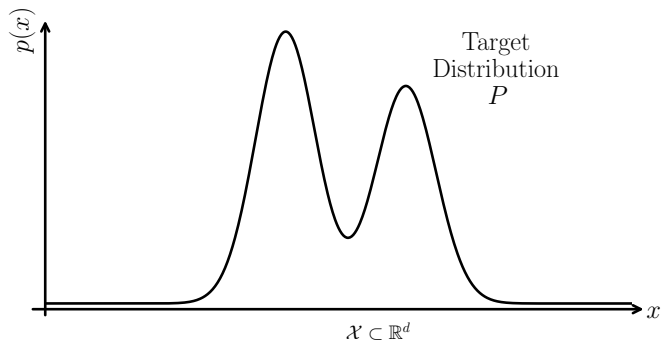
In this presentation, we discuss on *evaluating*, *optimizing* and *improving* quality and diversity of generative models:

1. **Evaluating:** How can we assess quality and diversity independently in Generative Models?
2. **Tuning:** Can we optimize a specific trade-off between quality and diversity?
3. **Improving:** How can we improve the quality and diversity of a pre-trained generative model?

Evaluating:
How can we assess quality and
diversity independently
in Generative Models?

GENERATIVE MODELS

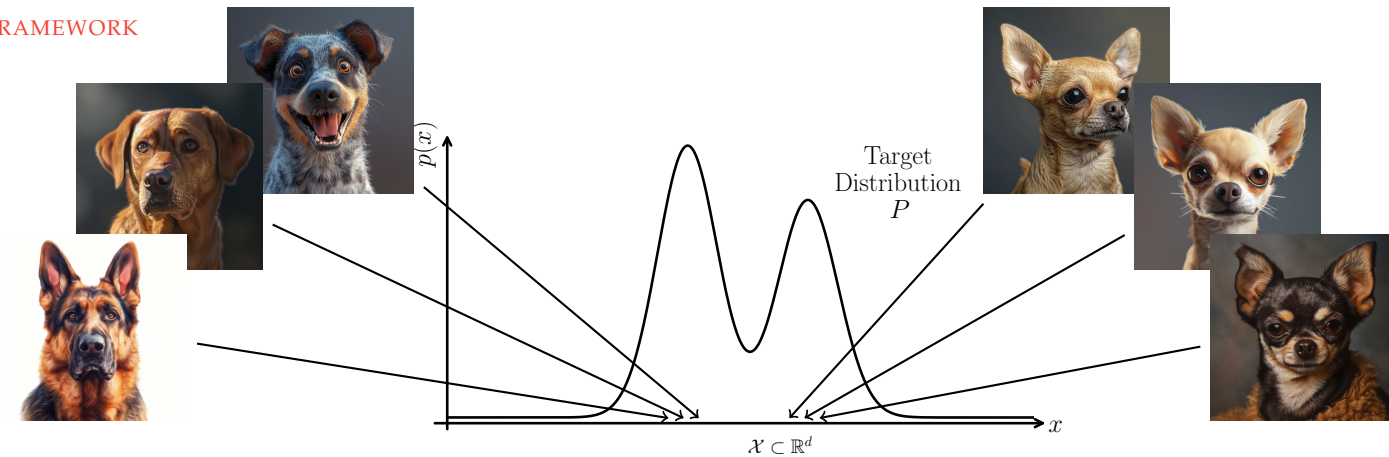
FRAMEWORK



- Assumption: There is an unknown *target distribution* P in $\mathcal{X} \subset \mathbb{R}^d$.

GENERATIVE MODELS

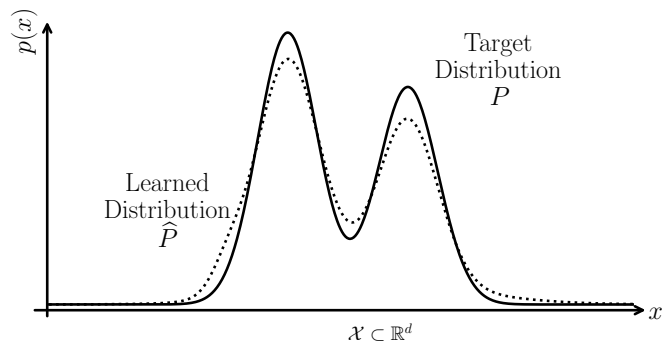
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GENERATIVE MODELS

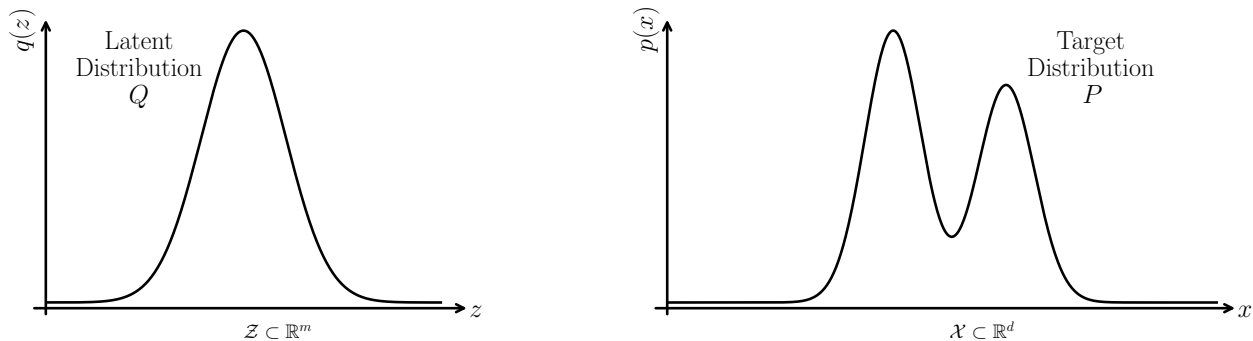
FRAMEWORK



- ▶ Assumption: There is an unknown *target distribution* P in $\mathcal{X} \subset \mathbb{R}^d$.
- ▶ Goal: Learn a *parameterized distribution* \hat{P} that approximate P :

GENERATIVE MODELS

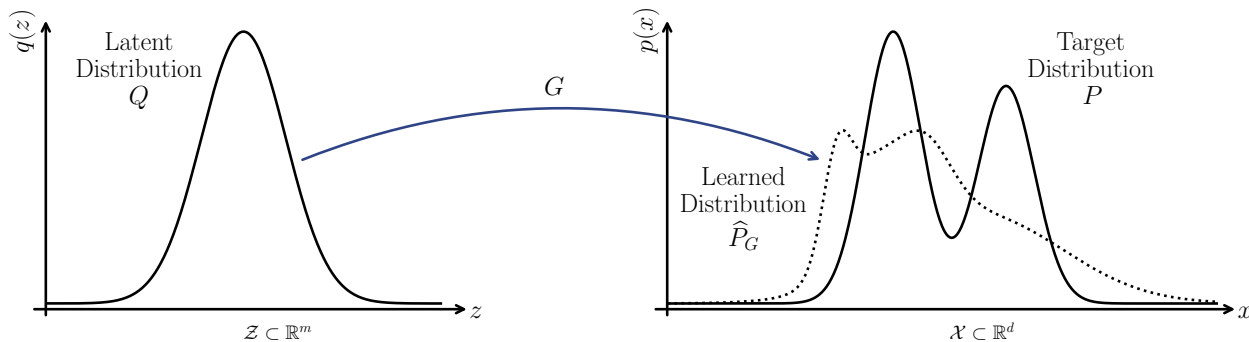
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 1. Consider a distribution Q in a *latent space* $\mathcal{Z} \subset \mathbb{R}^m$, usually $\mathcal{N}(0, I_m)$.

GENERATIVE MODELS

FRAMEWORK



- ▶ **Assumption:** There is an unknown *target distribution* P in $\mathcal{X} \subset \mathbb{R}^d$.
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GENERATIVE MODELS

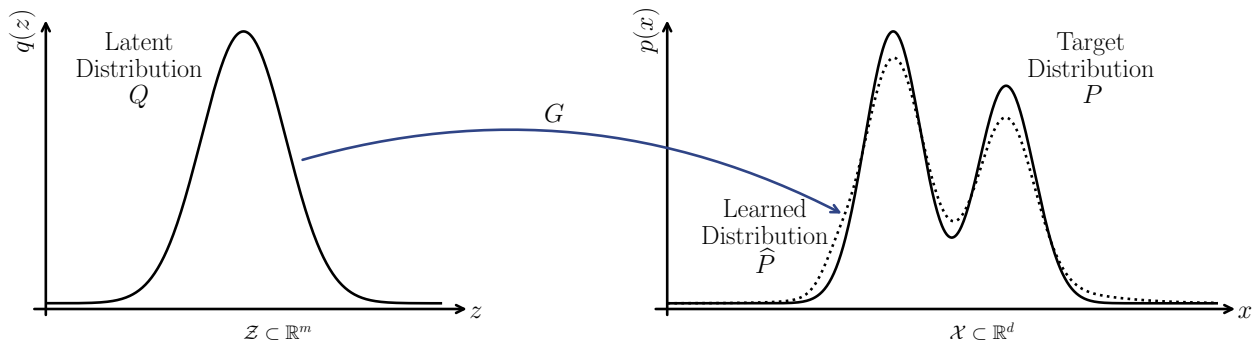
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 3. Compute G^{opt} that minimize a *dissimilarity measure* D between P and \hat{P}_G :

$$G^{\text{opt}} = \underset{G}{\operatorname{argmin}} D(P, \hat{P}_G)$$

GENERATIVE MODELS

FRAMEWORK



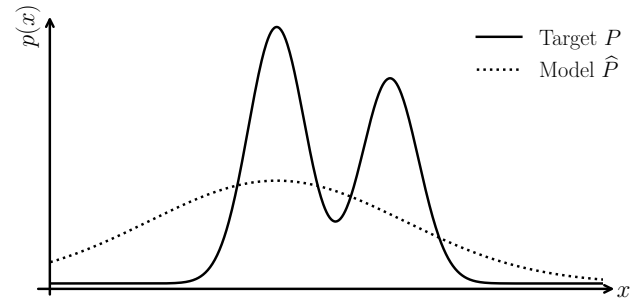
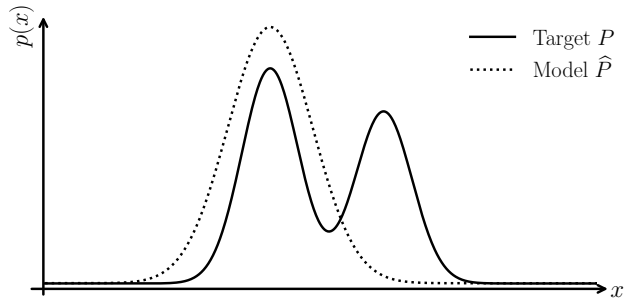
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GENERATIVE MODELS

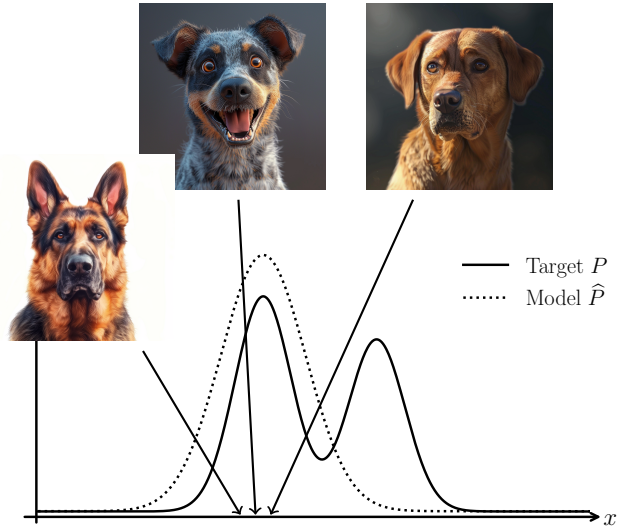
IN PRACTICE

$$\hat{P} \neq P$$

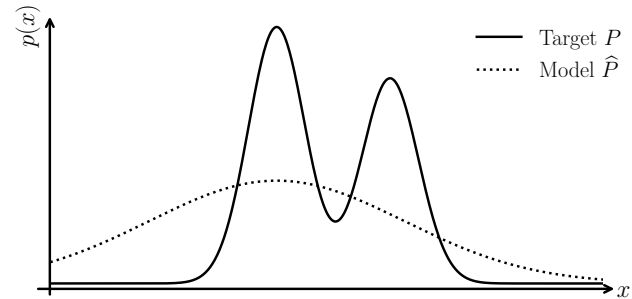


GENERATIVE MODELS

IN PRACTICE



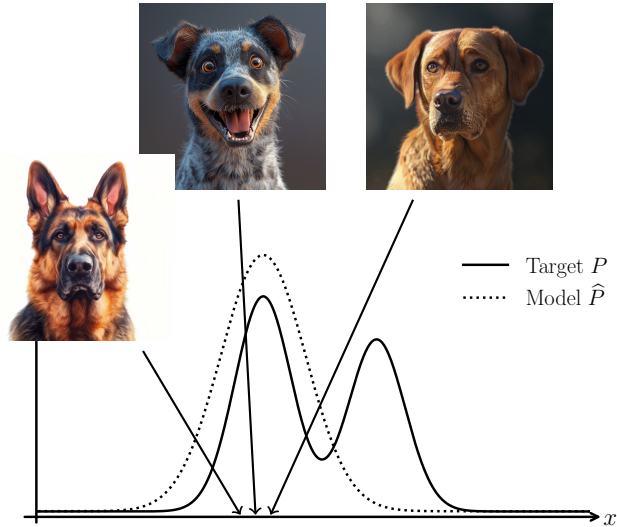
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Low Diversity

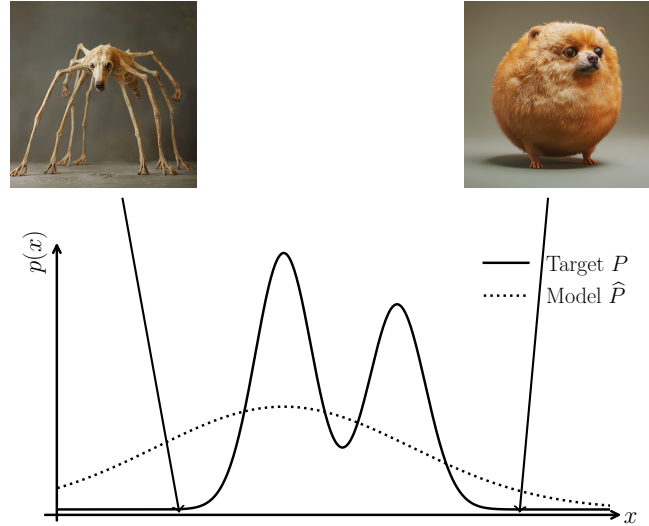
GENERATIVE MODELS

IN PRACTICE



Low Diversity

$$\hat{P} \neq P$$



Low Quality

PRECISION AND RECALL FOR GENERATIVE MODELS

METRICS TO EVALUATE QUALITY AND DIVERSITY

To assess models, we use the notion of Precision and Recall, inspired from Information Retrieval:

Quality

Diversity

PRECISION AND RECALL FOR GENERATIVE MODELS

METRICS TO EVALUATE QUALITY AND DIVERSITY

To assess models, we use the notion of Precision and Recall, inspired from Information Retrieval:

Quality

Diversity



Precision

=

What proportion of **generated** samples are **realistic**?

PRECISION AND RECALL FOR GENERATIVE MODELS

METRICS TO EVALUATE QUALITY AND DIVERSITY

To assess models, we use the notion of Precision and Recall, inspired from Information Retrieval:

Quality



Precision

=

What proportion of **generated** samples are **realistic**?

Diversity



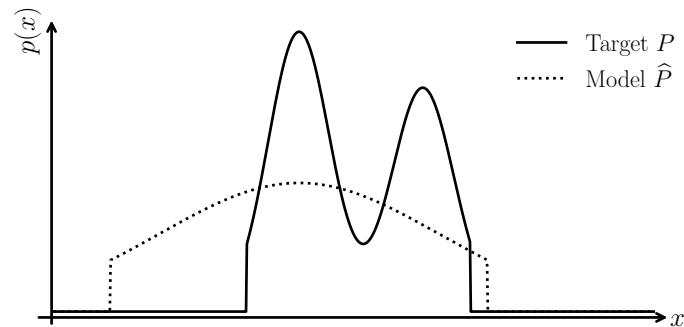
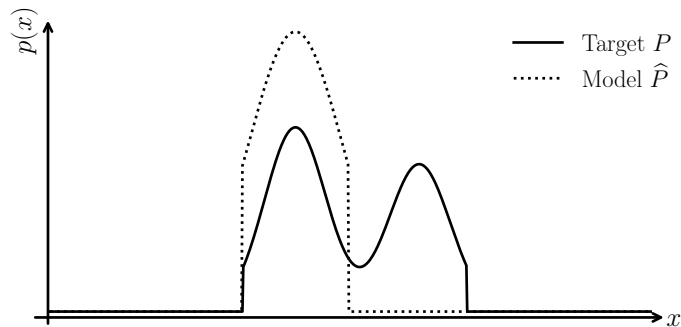
Recall

=

What proportion of **real** samples can be **generated**?

PRECISION AND RECALL FOR GENERATIVE MODELS

FOR FINITE SUPPORT



PRECISION AND RECALL FOR GENERATIVE MODELS

FOR FINITE SUPPORT

Definition 1.1 (Support-Based Precision and Recall - [15].)

For any distributions $P \in \mathcal{P}(\mathcal{X})$ and $\hat{P} \in \mathcal{P}(\mathcal{X})$, we say that the distribution P has precision $\bar{\alpha}$ at recall $\bar{\beta}$ with respect to \hat{P} if

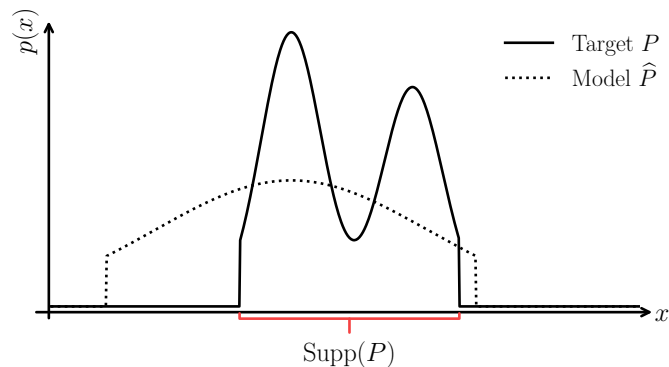
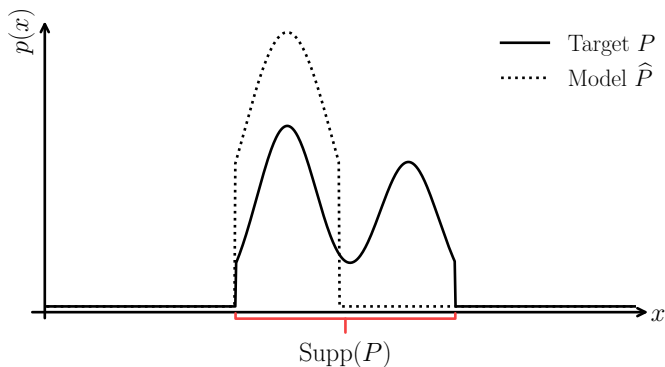
$$\bar{\alpha} := \hat{P}(\text{Supp}(P)) \quad \text{and} \quad \bar{\beta} := P(\text{Supp}(\hat{P})). \quad (1)$$

PRECISION AND RECALL FOR GENERATIVE MODELS

FOR FINITE SUPPORT

Precision for finite support is the proportion of generated data that lies on the support of the real data:

$$\bar{\alpha} = \hat{P}(\text{Supp}(P)).$$

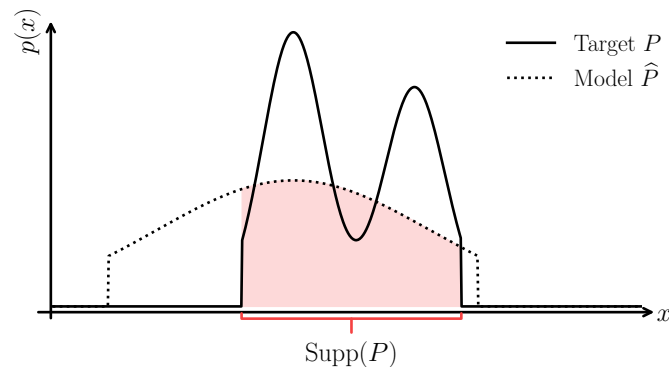
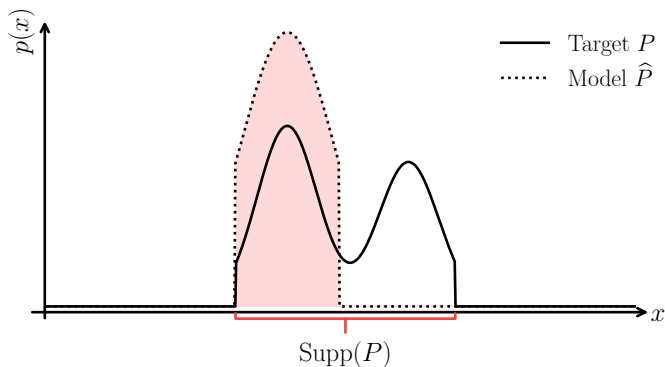


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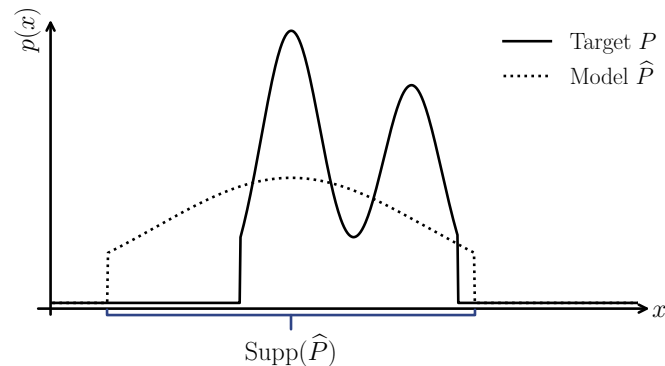
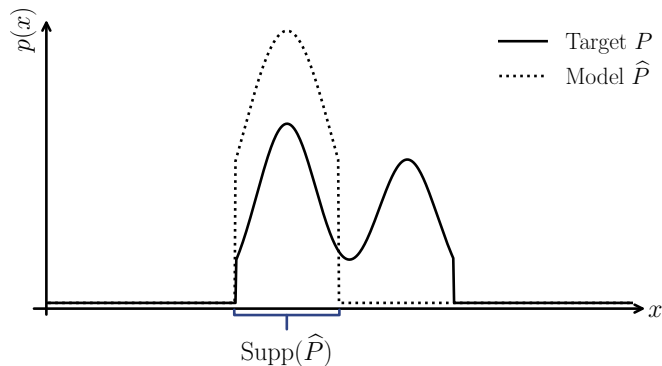


PRECISION AND RECALL FOR GENERATIVE MODELS

FOR FINITE SUPPORT

Recall for finite support is the proportion of the support of the real data that is covered by the generated data:

$$\bar{\beta} = P(\text{Supp}(\hat{P})).$$

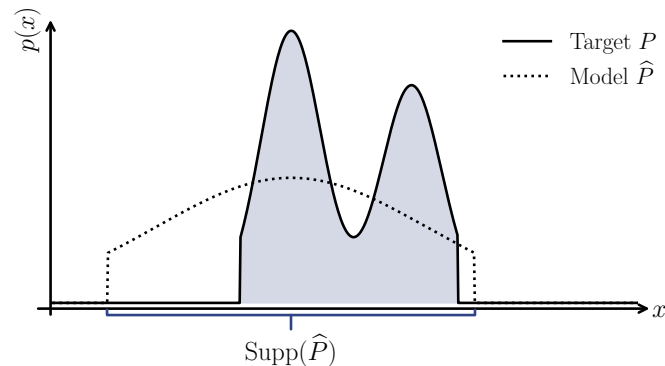
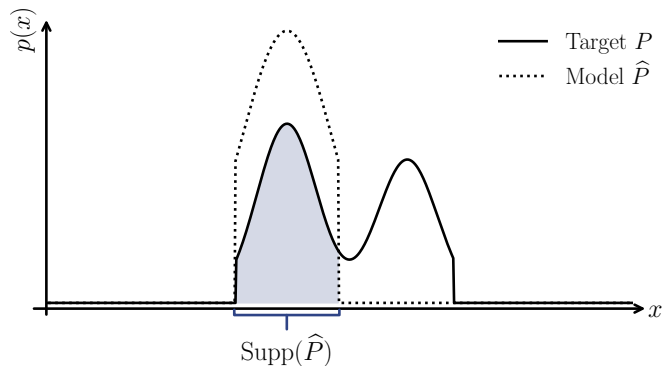


PRECISION AND RECALL FOR GENERATIVE MODELS

FOR FINITE SUPPORT

Recall for finite support is the proportion of the support of the real data that is covered by the generated data:

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PRECISION AND RECALL FOR GENERATIVE MODELS

IN PRACTICE

MNIST Dataset [26]



PRECISION AND RECALL FOR GENERATIVE MODELS

IN PRACTICE

Low Precision High Recall



Precision: 0.54 Recall: 0.91

MNIST Dataset [26]



High Precision Low Recall

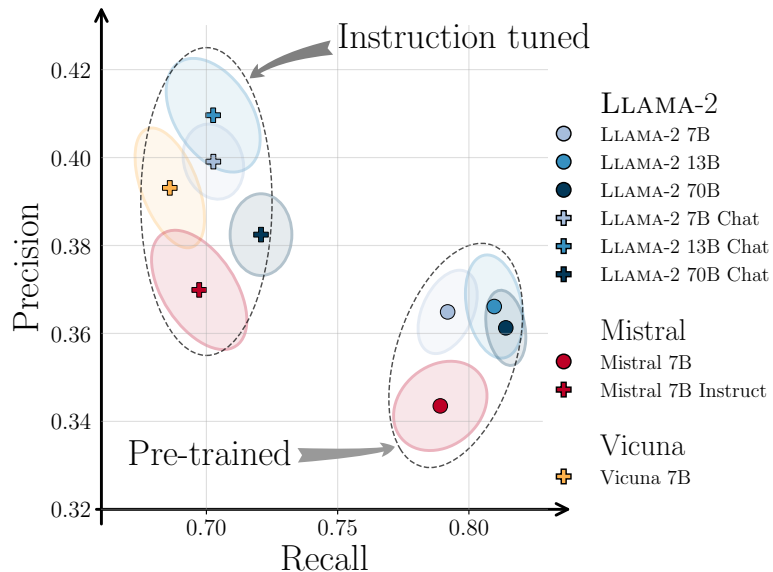


Precision: 0.80 Recall: 0.70

PRECISION AND RECALL FOR GENERATIVE MODELS

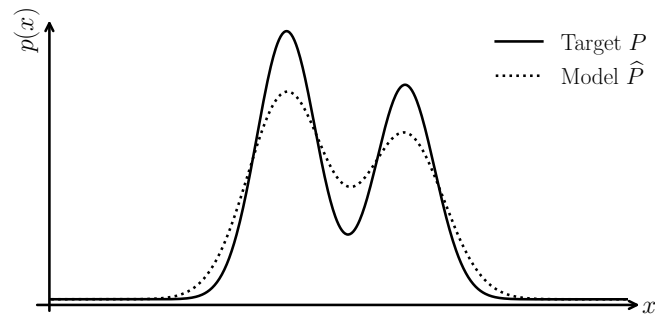
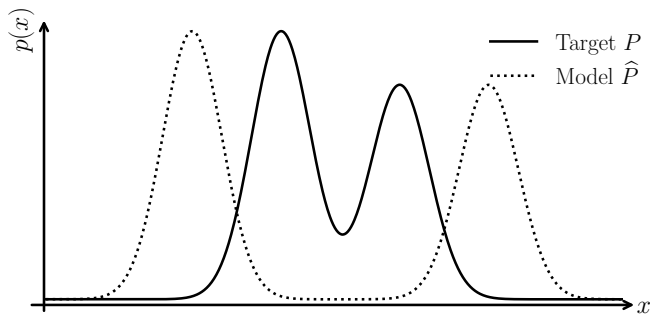
FOR LLMs

On open-ended generation, the quality and diversity of LLMs can also be evaluated using Precision and Recall: Bronnec et al. [6]



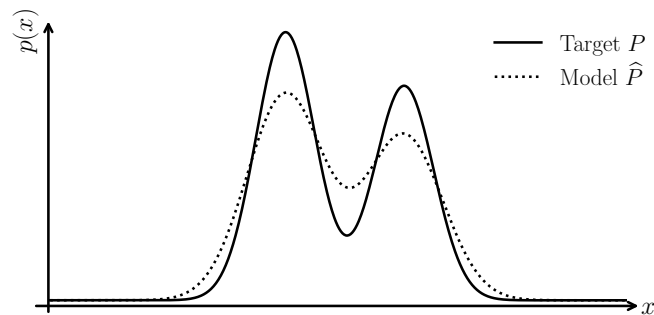
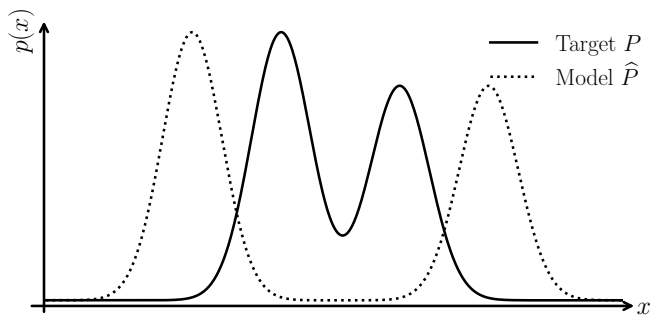
PRECISION AND RECALL FOR GENERATIVE MODELS

FOR INFINITE SUPPORT



PRECISION AND RECALL FOR GENERATIVE MODELS

FOR INFINITE SUPPORT



Both distributions have **perfect** Precision *and* Recall.

PR-CURVE FOR GENERATIVE MODELS

DEFINITION

Definition 1.2 (PR-Curve for Generative Models - Sajjadi et al. [19], Simon et al. [20])

Let $P, \hat{P} \in \mathcal{P}(\mathcal{X})$ be two distributions such that $P, \hat{P} \ll \mu$. The PR-Curve is the set $\text{PRD}(P, \hat{P})$ defined as:

$$\text{PRD}(P, \hat{P}) = \{(\alpha_\lambda, \beta_\lambda) \mid \lambda \in [0, \infty]\} \quad (2)$$

with:

$$\alpha_\lambda = \int_{\mathcal{X}} \min(\lambda p(\mathbf{x}), \hat{p}(\mathbf{x})) \, \mathrm{d}\mu(\mathbf{x}) \quad \text{and} \quad \beta_\lambda = \int_{\mathcal{X}} \min(p(\mathbf{x}), \hat{p}(\mathbf{x})/\lambda) \, \mathrm{d}\mu(\mathbf{x}). \quad (3)$$

PR-CURVE FOR GENERATIVE MODELS

DEFINITION

For the Precision, λp is compared to \hat{p} for different threshold $\lambda \in [0, +\infty]$:

$$\alpha_\lambda = \int_{\mathcal{X}} \min(\lambda p(\mathbf{x}), \hat{p}(\mathbf{x})) \, \mathrm{d}\mu(\mathbf{x}) \quad (4)$$

PR-CURVE FOR GENERATIVE MODELS

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PR-CURVE FOR GENERATIVE MODELS

DEFINITION

For the Recall, p is compared to \hat{p}/λ for different threshold $\lambda \in [0, +\infty]$:

$$\beta_\lambda = \int_{\mathcal{X}} \min(p(\mathbf{x}), \hat{p}(\mathbf{x})/\lambda) \, d\mu(\mathbf{x}) \quad (5)$$

PR-CURVE FOR GENERATIVE MODELS

DEFINITION

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PR-CURVE FOR GENERATIVE MODELS

EXAMPLES

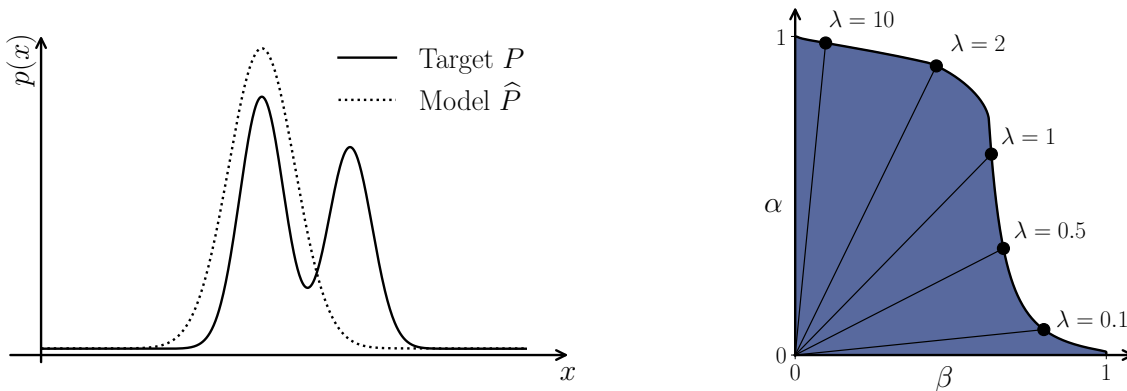


Figure. Learning distribution with low recall and high precision.

PR-CURVE FOR GENERATIVE MODELS

EXAMPLES

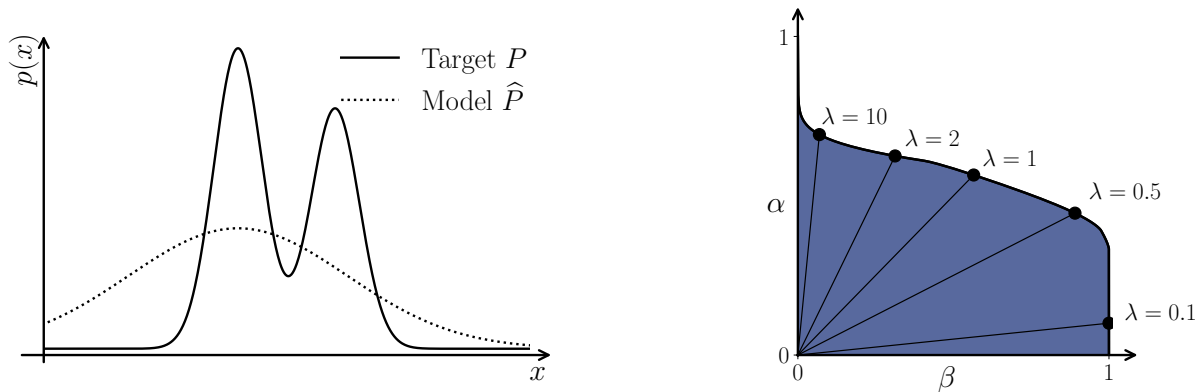


Figure. Learning distribution with high recall and low precision.

PR-CURVE FOR GENERATIVE MODELS

EXAMPLES

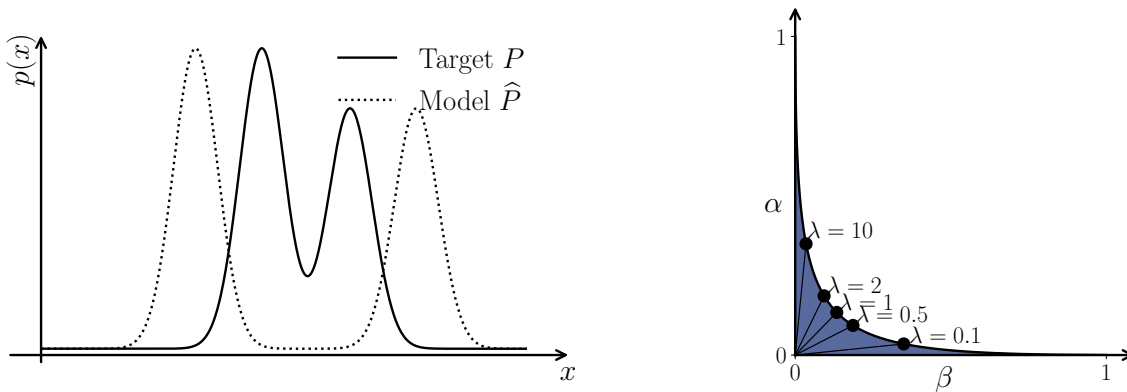


Figure. Learning distribution with **low recall** and **low precision**.

PR-CURVE FOR GENERATIVE MODELS

EXAMPLES

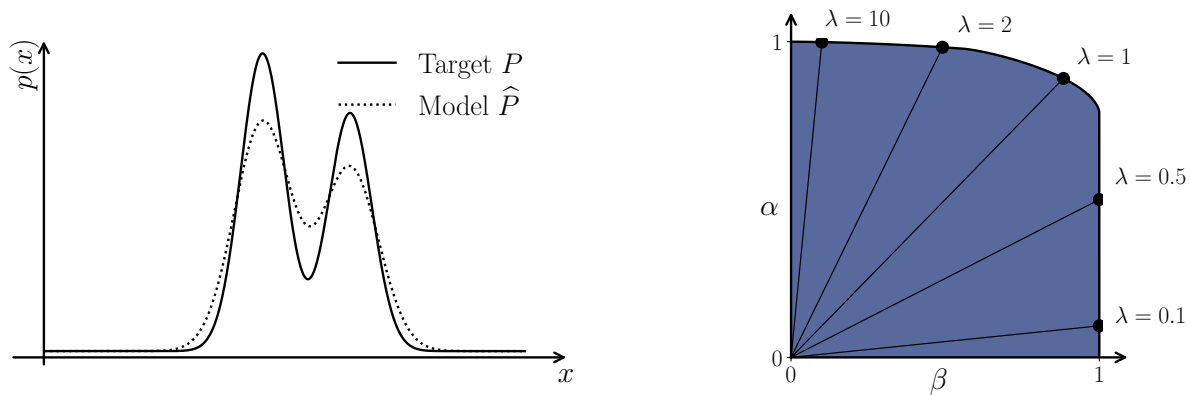


Figure. Learning distribution with high recall and high precision.

PR-CURVE AND SUPPORT-BASED PRECISION AND RECALL RELATION

The PR-Curve is a generalization of the Precision and Recall for finite support:

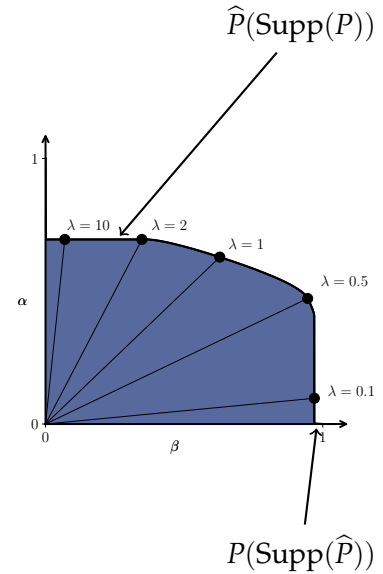
Theorem 1.3 (Support-based and PR-Curves - Siry et al. [21])

Let $P, \hat{P} \in \mathcal{P}(\mathcal{X})$ be two distributions. Then, the support-based Precision and Recall $(\bar{\alpha}, \bar{\beta})$ are related to the PR-Curve values $\text{PRD}(P, \hat{P})$ for $\lambda = 0$ and $\lambda = \infty$:

$$\bar{\alpha} = \max_{\lambda} \alpha_{\lambda} = \alpha_{\infty} \quad \text{and} \quad \bar{\beta} = \max_{\lambda} \beta_{\lambda} = \beta_0. \quad (6)$$

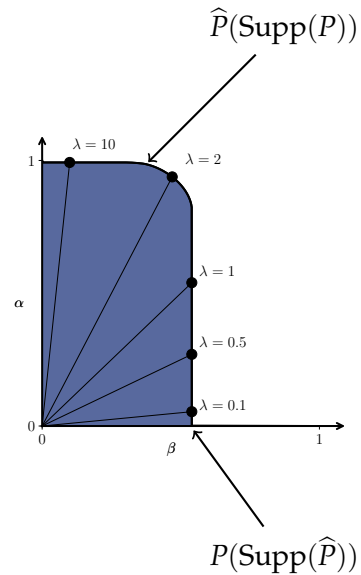
PR-CURVE AND SUPPORT-BASED PRECISION AND RECALL

RELATION



PR-CURVE AND SUPPORT-BASED PRECISION AND RECALL

RELATION



PR-CURVE FOR GENERATIVE MODELS

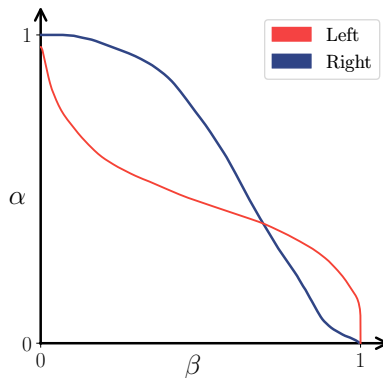
IN PRACTICE

Low Precision High Recall



Precision: 0.54 Recall: 0.91

PR-Curves



High Precision Low Recall



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PR-CURVE FOR GENERATIVE MODELS

IN NLP

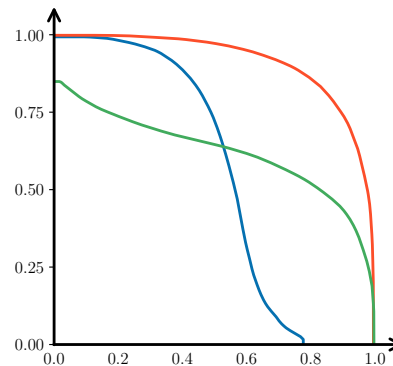
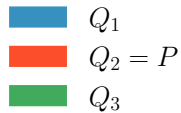
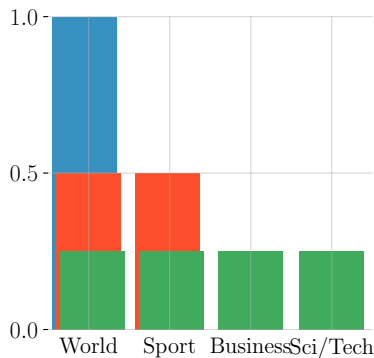


Figure. PR-Curve for distributions journal articles: AG News.

ON THE PLATFORM

Metrics used to evaluate your models are:

- ▶ FID
- ▶ Precision (for finite support)
- ▶ Recall (for finite support)
- ▶ (Obviously) the visual inspection of the generated samples.

Tuning:
How can we tune a model to
a specific trade-off between
Precision and Recall?

GENERATIVE ADVERSARIAL NETWORKS

ORIGINAL FRAMEWORK

- ▶ Let $G : \mathcal{Z} \rightarrow \mathcal{X}$ be a generator model parameterized by a neural network.
- ▶ Let $D : \mathcal{X} \rightarrow [0, 1]$ be a discriminator model parameterized by a neural network.

The original GAN framework [8] is defined by the following optimization problem:

$$\min_G \max_D \mathbb{E}_{\mathbf{x} \sim P} [\log D(\mathbf{x})] + \mathbb{E}_{\mathbf{x} \sim \hat{P}_G} [\log(1 - D(\mathbf{x}))]. \quad (6)$$

TUNING PRECISION AND RECALL IN GENERATIVE MODELS

TRUNCATION

Hard Truncation

Karras et al. [13]

Soft Truncation

Kingma and Dhariwal [14]

TUNING PRECISION AND RECALL IN GENERATIVE MODELS

HARD TRUNCATION



Figure. From left to right: $\psi = 0.0$, $\psi = 0.3$ $\psi = 0.7$ $\psi = 1.0$.

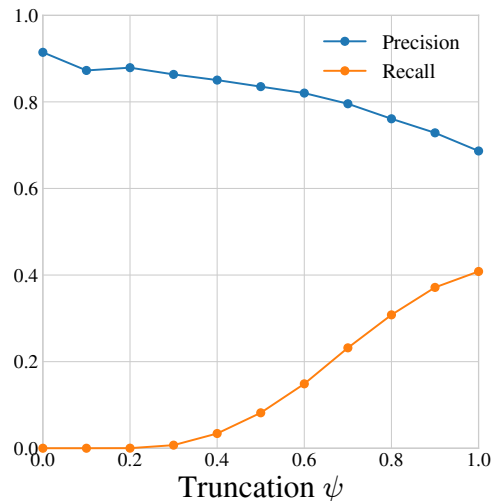


Figure. Source: [15]

TUNING PRECISION AND RECALL IN GENERATIVE MODELS

SOFT TRUNCATION

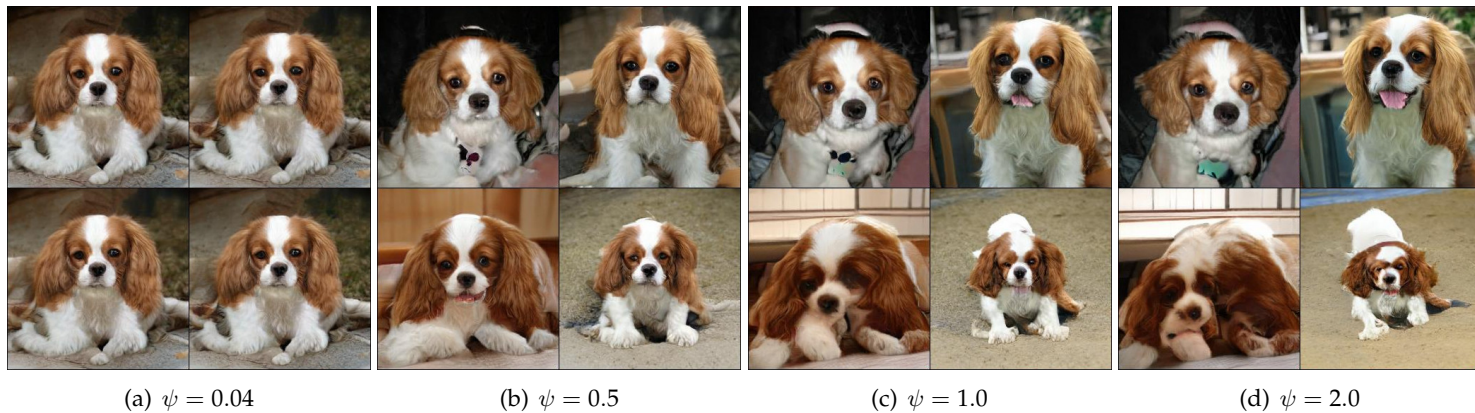


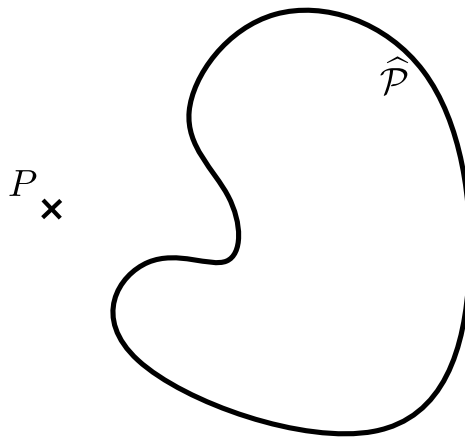
Figure. Soft-Truncation on BigGAN. Source:[5].

TRAINING A GENERATIVE MODEL

IN GENERAL

Traditionally, the goal is to minimize *a dissimilarity measure* between the target distribution P and the learned distribution \hat{P} :

$$\min_G D(P, \hat{P}_G) \quad (7)$$



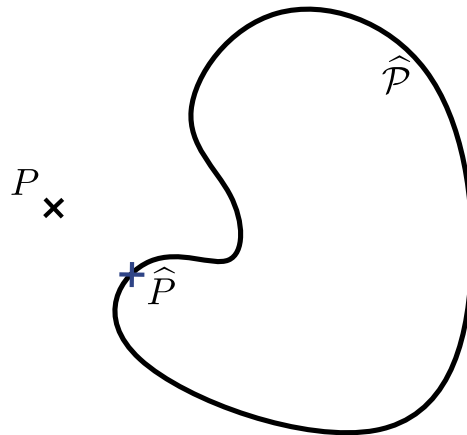
Distribution Space

TRAINING A GENERATIVE MODEL

WITH f -DIVERGENCES

Traditionally, the goal is to minimize *an f -divergence* between the target distribution P and the learned distribution \hat{P} :

$$\min_G \mathcal{D}_f(P \parallel \hat{P}_G) \quad (7)$$



Distribution Space

f -DIVERGENCES

DEFINITION

Definition 2.1 (f -divergences)

For any two probability distributions P and \hat{P} in $\mathcal{P}(\mathcal{X})$ such that $P, \hat{P} \ll \mu$. Let p and \hat{p} be the Radon-Nikodym densities of P and \hat{P} with respect to μ , respectively. Let f be any convex lower semi-continuous function $f : [0, \infty] \rightarrow]-\infty, +\infty]$ such that $f(1) = 0$, the f -divergence between P and \hat{P} is

$$\mathcal{D}_f(P||\hat{P}) = \int_{\mathcal{X}} \hat{p}(\mathbf{x}) f\left(\frac{p(\mathbf{x})}{\hat{p}(\mathbf{x})}\right) d\mu(\mathbf{x}). \quad (8)$$

f -DIVERGENCES

DEFINITION

Definition 2.1 (f -divergences)

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Usual divergences are f -divergences:

- ▶ Kullback-Leibler (KL),
- ▶ Reverse Kullback-Leibler (rKL),
- ▶ Jensen-Shannon (JS),
- ▶ Total Variation (TV),
- ▶ α -divergences.

ESTIMATING f -DIVERGENCES

DUAL VARIATIONAL FORM

f -divergences are *hardly tractable* in practice. However, they can be approximated by a dual approximation.

ESTIMATING f -DIVERGENCES

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- ▶ $f^*(t) = \sup_{u \in \mathbb{R}} \{tu - f(u)\}$ be *the Fenchel conjugate* of f .
- ▶ \mathcal{T} be the set of all measurable functions $\mathcal{X} \rightarrow \mathbb{R}$.

ESTIMATING f -DIVERGENCES

DUAL VARIATIONAL FORM

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- ▶ \mathcal{T} be the set of all measurable functions $\mathcal{X} \rightarrow \mathbb{R}$.

Theorem 2.2 (Dual variational form of an f -divergence- Nguyen et al. [16])

Let $P, \hat{P} \in \mathcal{P}(\mathcal{X})$ two distributions such that P is absolutely continuous with respect to \hat{P} and f a suitable generator function. The f -divergence between P and \hat{P} admits a dual variational form:

$$\mathcal{D}_f(P \parallel \hat{P}) = \sup_{T \in \mathcal{T}} (\mathbb{E}_{\mathbf{x} \sim P} [T(\mathbf{x})] - \mathbb{E}_{\mathbf{x} \sim \hat{P}} [f^*(T(\mathbf{x}))]). \quad (9)$$

We use $T^{\text{opt}} \in \mathcal{T}$ to denote the function that achieves the supremum.

TRAINING A GENERATIVE MODEL WITH f -DIVERGENCES

USING THE DUAL VARIATIONAL FORM

By doing so, we can rewrite the optimization problem as:

$$\min_G \max_T \underbrace{\mathbb{E}_{\mathbf{x} \sim P} [T(\mathbf{x})] - \mathbb{E}_{\mathbf{x} \sim \hat{P}_G} [f^*(T(\mathbf{x}))]}_{\mathcal{D}_{f,T}^{\text{dual}}} \quad (10)$$

TRAINING A GENERATIVE MODEL WITH f -DIVERGENCES

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- ▶ The discriminator T is trained *to estimate* the divergence.
- ▶ The generator G is trained *to minimize* the divergence.

TRAINING A GENERATIVE MODEL WITH f -DIVERGENCES

USING THE DUAL VARIATIONAL FORM

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TRAINING A GENERATIVE MODEL WITH f -DIVERGENCES

USING THE DUAL VARIATIONAL FORM

By doing so, we can rewrite the optimization problem as:

$$\min_G \max_T \mathbb{E}_{\mathbf{x} \sim P} [\log(D(\mathbf{x}))] - \mathbb{E}_{\mathbf{x} \sim \hat{P}_G} [f^*(\log(D(\mathbf{x})))] \quad (10)$$

- ▶ The discriminator T is trained *to estimate* the divergence.
- ▶ The generator G is trained *to minimize* the divergence.
- ▶ With $T(\mathbf{x}) = \log(D(\mathbf{x}))$ with $D(\mathbf{x}) \in [0, 1]$.

TRAINING A GENERATIVE MODEL WITH f -DIVERGENCES

USING THE DUAL VARIATIONAL FORM

By doing so, we can rewrite the optimization problem as:

$$\min_G \max_T \mathbb{E}_{\mathbf{x} \sim P} [\log(D(\mathbf{x}))] + \mathbb{E}_{\mathbf{x} \sim \hat{P}_G} [\log(1 - D(\mathbf{x}))] \quad (10)$$

- ▶ The discriminator T is trained *to estimate* the divergence.
- ▶ The generator G is trained *to minimize* the divergence.
- ▶ With $T(\mathbf{x}) = \log(D(\mathbf{x}))$ with $D(\mathbf{x}) \in [0, 1]$.
- ▶ $f^*(t) = f_{\text{JS}}^*(t) = -\log(1 - \exp(t))$ for the Jensen-Shannon divergence.

We recover the original GAN framework.

TRAINING A GENERATIVE MODEL WITH f -DIVERGENCES

USING THE DUAL VARIATIONAL FORM

By doing so, we can rewrite the optimization problem as:

$$\min_G \max_T \underbrace{\mathbb{E}_{\mathbf{x} \sim P} [T(\mathbf{x})] - \mathbb{E}_{\mathbf{x} \sim \hat{P}_G} [f^*(T(\mathbf{x}))]}_{\mathcal{D}_{f,T}^{\text{dual}}} \quad (10)$$

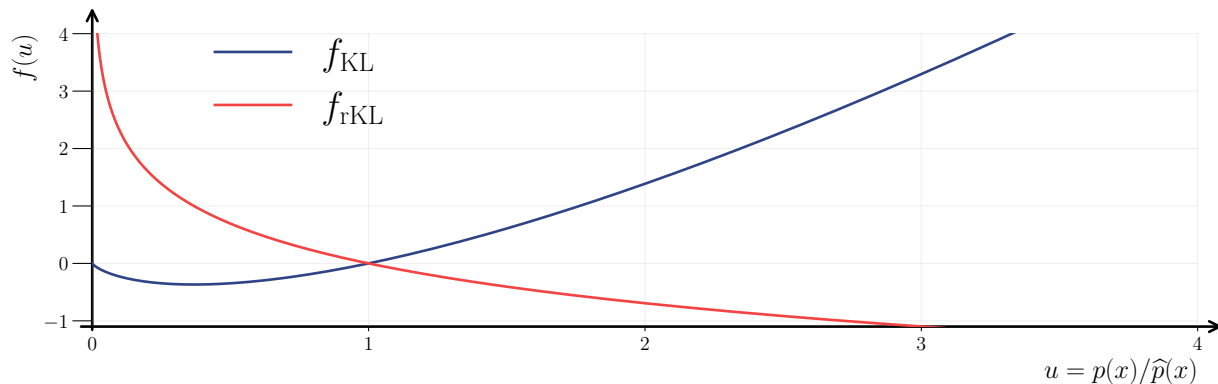
- ▶ The discriminator T is trained *to estimate* the divergence.
- ▶ The generator G is trained *to minimize* the divergence.

- ▶ Generative Adversarial Networks [8] for *the Jensen-Shannon divergence*.
- ▶ Extended to other f -divergences by Nowozin et al. [17].
- ▶ Extend to other generative models such as Normalizing Flows by Grover et al. [9].

EFFECT OF THE f -DIVERGENCE ON THE LEARNED DISTRIBUTION

All f -divergences are not equal:

$$\mathcal{D}_f(P||\hat{P}) = \mathbb{E}_{\mathbf{x} \sim \hat{P}} \left[f \left(\frac{p(\mathbf{x})}{\hat{p}(\mathbf{x})} \right) \right]$$

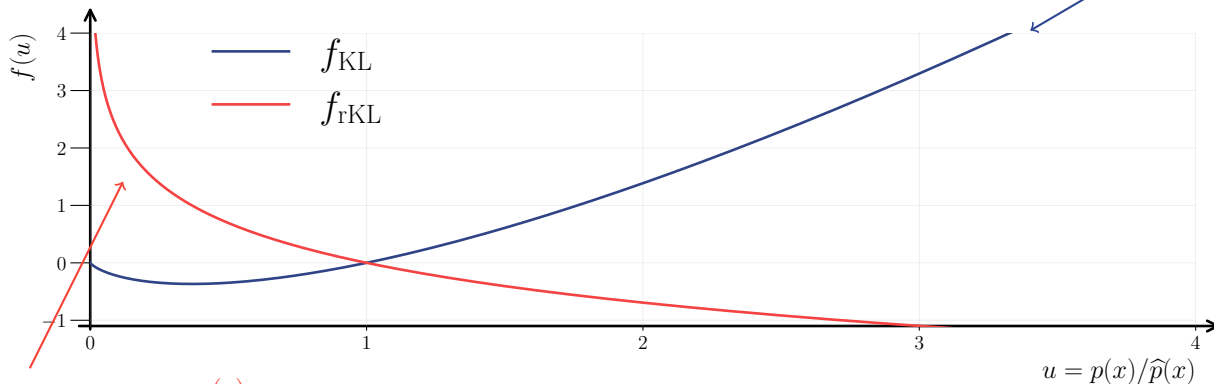


EFFECT OF THE f -DIVERGENCE ON THE LEARNED DISTRIBUTION

All f -divergences are not equal:

$$\mathcal{D}_f(P\|\hat{P}) = \mathbb{E}_{x\sim\hat{P}} \left[f \left(\frac{p(x)}{\hat{p}(x)} \right) \right]$$

Penalizing high values of $\frac{p(x)}{\hat{p}(x)}$



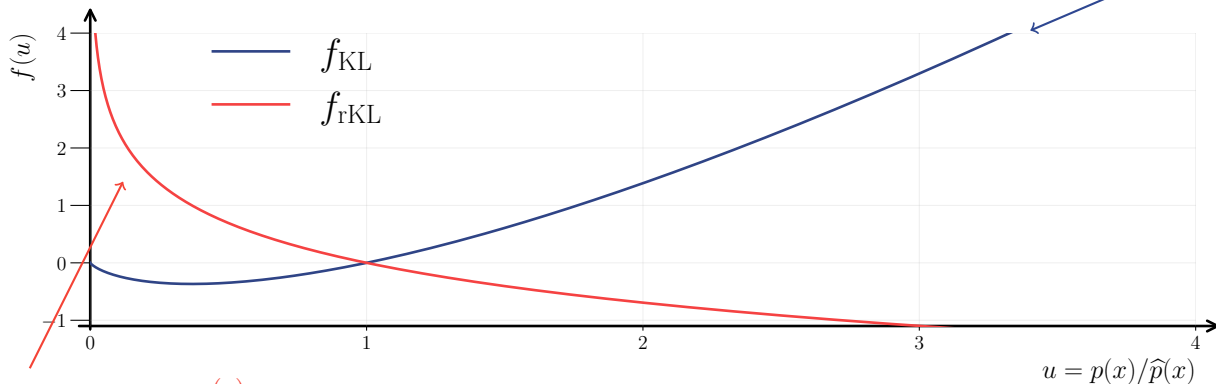
Penalizing low values of $\frac{p(x)}{\hat{p}(x)}$

EFFECT OF THE f -DIVERGENCE ON THE LEARNED DISTRIBUTION

All f -divergences are not equal:

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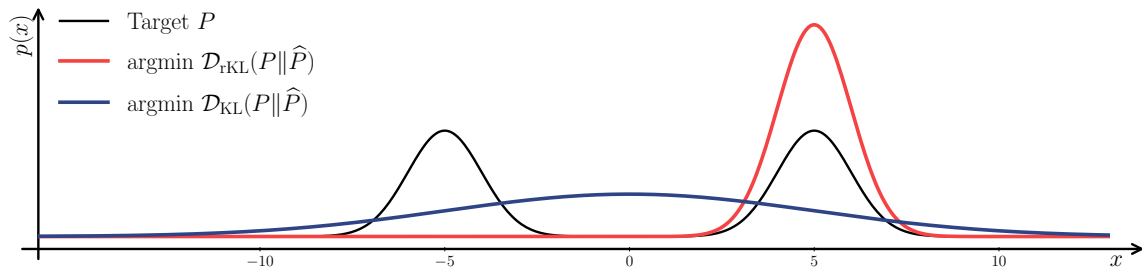
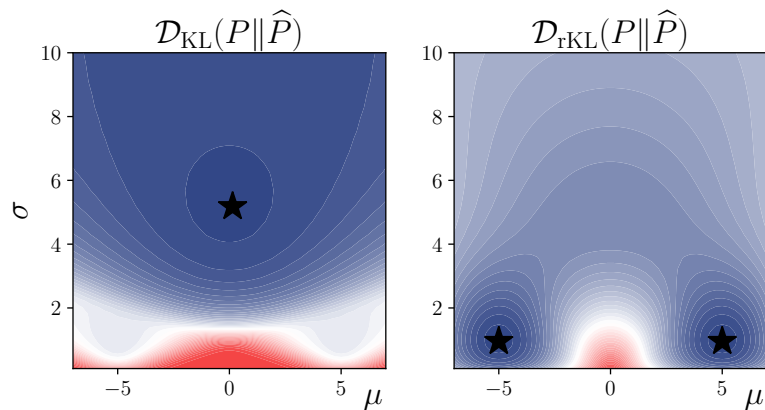
Penalizing high values of $\frac{p(x)}{\hat{p}(x)}$
Favors high recall



Penalizing low values of $\frac{p(x)}{\hat{p}(x)}$
Favors high precision

EXAMPLES OF f -DIVERGENCE MINIMIZATION

EXAMPLES OF f -DIVERGENCE MINIMIZATION



TUNING PRECISION AND RECALL IN GENERATIVE MODELS

CONTRIBUTIONS

Can we optimize a specific trade-off between Precision and Recall?

TUNING PRECISION AND RECALL IN GENERATIVE MODELS

CONTRIBUTIONS

Can we optimize a specific trade-off between Precision and Recall?

- ▶ What is the relation between the Precision-Recall curve and f -divergences?

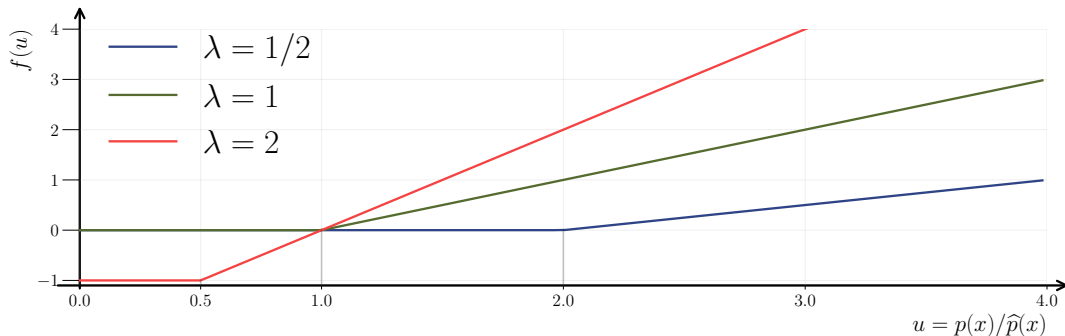
PRECISION-RECALL DIVERGENCE

DEFINITION

Definition 2.3 (PR-Divergence generator function f_λ)

Given a trade-off parameter $\lambda \in [0, +\infty]$, we define the generator function $f_\lambda : [0, +\infty] \rightarrow]-\infty, +\infty]$ given by

$$f_\lambda(u) = \begin{cases} \max(\lambda u, 1) - \max(\lambda, 1) & \text{for } \lambda \in [0, +\infty[, \\ \mathbb{1}_{\{u=0\}} & \text{for } \lambda = +\infty. \end{cases} \quad (11)$$



PRECISION-RECALL DIVERGENCE

PROPERTIES

Proposition 2.4 (PR-Divergence)

For any distributions $P, \hat{P} \in \mathcal{P}(\mathcal{X})$ such that $P, \hat{P} \ll \mu$, then for any $\lambda \in [0, +\infty]$ the PR-Divergence defined as

$$\mathcal{D}_{\lambda\text{-PR}}(P \parallel \hat{P}) = \int_{\mathcal{X}} \hat{p}(x) f_{\lambda} \left(\frac{p(x)}{\hat{p}(x)} \right) d\mu(x) \quad (12)$$

belongs to the class of f -divergences.

PRECISION-RECALL DIVERGENCE

LINKING THE PR-DIVERGENCE TO THE PR-CURVE

Theorem 2.5 (PR-Curves as a function of $\mathcal{D}_{\lambda\text{-PR}}$)

Given $P, \hat{P} \in \mathcal{P}(\mathcal{X})$ such that $P, \hat{P} \ll \mu$ and $\lambda \in [0, +\infty]$, the PR-Curve ∂PRD is related to the PR-Divergence $\mathcal{D}_{\lambda\text{-PR}}(P||\hat{P})$ as follows.

$$\alpha_{\lambda}(P||\hat{P}) = \min(1, \lambda) - \mathcal{D}_{\lambda\text{-PR}}(P||\hat{P}).$$

$$\beta_{\lambda}(P||\hat{P}) = \min(1, \lambda) - \mathcal{D}_{\lambda\text{-PR}}(\hat{P}||P).$$

PRECISION-RECALL DIVERGENCE

LINKING THE PR-DIVERGENCE TO THE PR-CURVE

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$$\beta_{\lambda}(P||\hat{P}) = \min(1, \lambda) - \mathcal{D}_{\lambda\text{-PR}}(\hat{P}||P).$$

A direct consequence of Theorem 2.5:

$$\operatorname{argmin}_{\hat{P} \in \mathcal{P}(\mathcal{X})} \mathcal{D}_{\lambda\text{-PR}}(P||\hat{P}) = \operatorname{argmax}_{\hat{P} \in \mathcal{P}(\mathcal{X})} \alpha_{\lambda}(P||\hat{P}).$$

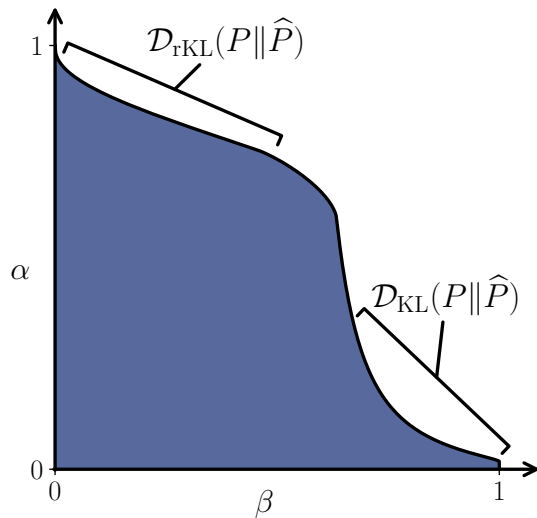
EXPLAINING QUALITY/DIVERSITY

CONNECTION BETWEEN PR-DIVERGENCE AND f -DIVERGENCES

Theorem 2.6 (f -divergences as a weighted average of PR-Divergences)

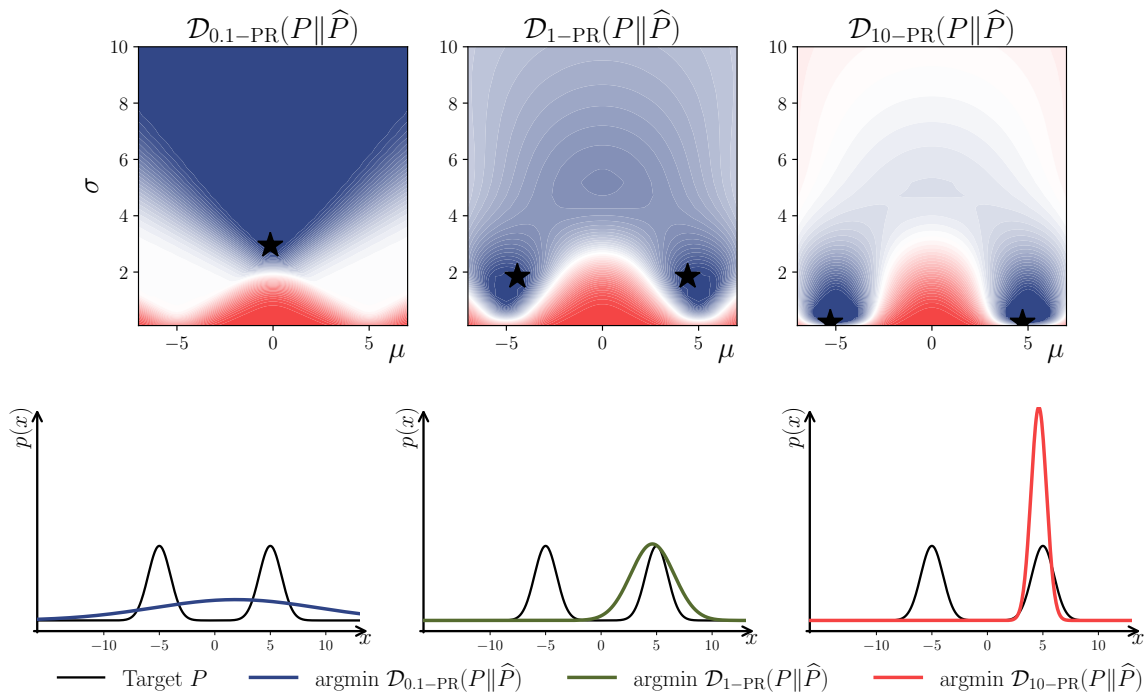
For any $P, \hat{P} \in \mathcal{P}(\mathcal{X})$ supported on all \mathcal{X} and any $\lambda \in [0, +\infty]$, then:

$$\mathcal{D}_f(P\|\hat{P}) = \int_0^\infty \frac{1}{\lambda^3} f''\left(\frac{1}{\lambda}\right) \mathcal{D}_{\lambda\text{-PR}}(P\|\hat{P}) d\lambda,$$



OPTIMIZING THE PR-DIVERGENCE

EXAMPLES



OPTIMIZING THE PR-DIVERGENCE

EXAMPLES

OPTIMIZING THE PR-DIVERGENCE WITH OUR APPROACH

IN PRACTICE



(a) $\lambda = 0.1$



(b) $\lambda = 1$



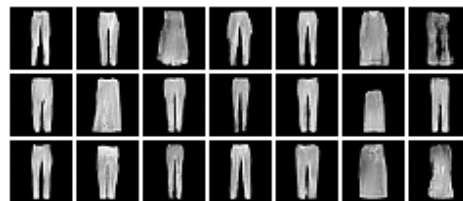
(c) $\lambda = 10$



(d) $\lambda = 0.1$



(e) $\lambda = 1$



(f) $\lambda = 10$

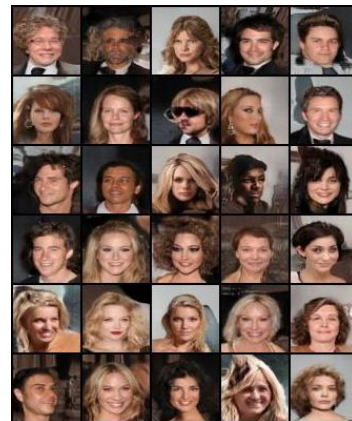
OPTIMIZING THE PR-DIVERGENCE WITH OUR APPROACH

TRAINING GANs

Model	CIFAR-10 32×32			CelebA 64×64		
	FID	P	R	FID	P	R
Baseline Big-GAN	13.37	86.51	65.66	9.16	78.41	51.42
$\lambda = 0.05$	13.29	81.10	70.63	-	-	-
$\lambda = 0.1$	11.62	81.78	74.58	-	-	-
$\lambda = 0.2$	13.36	84.85	65.13	8.79	83.37	44.07
$\lambda = 0.5$	14.50	83.27	68.23	6.03	77.60	55.98
$\lambda = 1.0$	14.03	83.04	69.35	13.07	81.70	36.85
$\lambda = 2.0$	16.94	84.93	59.79	14.23	82.98	32.87
$\lambda = 5.0$	32.54	83.39	56.94	22.45	83.96	25.81
$\lambda = 10.0$	39.69	84.11	39.29	-	-	-
$\lambda = 20.0$	67.03	90.03	21.81	-	-	-



$\lambda = 0.1$



$\lambda = 10$

When λ increases, $\left\{ \begin{array}{l} \text{Precision } \uparrow \\ \text{Recall } \downarrow \end{array} \right.$

OPTIMIZING THE PR-DIVERGENCE WITH OUR APPROACH

FINE-TUNING GANS

Model	ImageNet 128×128			FFHQ 256×256		
	FID	P	R	FID	P	R
Baseline BigGAN	9.83	28.04	41.21	41.41	65.57	10.17
Soft $\psi = 0.7$	11.39	23.04	31.13	56.43	76.59	4.87
Soft $\psi = 0.5$	15.49	20.20	19.83	82.05	84.48	1.58
Hard $\psi = 2.0$	9.69	25.83	39.89	43.32	68.84	8.66
Hard $\psi = 1.0$	12.12	21.86	35.42	56.19	76.44	4.76
Hard $\psi = 0.5$	15.21	21.13	29.55	71.32	80.99	4.84
$\lambda = 0.2$	9.92	26.69	42.04	35.66	78.70	9.45
$\lambda = 0.5$	10.82	26.83	42.38	35.24	78.41	9.66
$\lambda = 1.0$	20.42	29.72	28.21	35.91	78.95	8.32
$\lambda = 2.0$	20.21	30.27	30.49	36.33	81.10	8.69
$\lambda = 5.0$	20.76	30.87	28.38	38.16	84.31	8.52

When λ increases, $\left\{ \begin{array}{l} \text{Precision } \uparrow \\ \text{Recall } \downarrow \end{array} \right.$ with better performances than truncation.

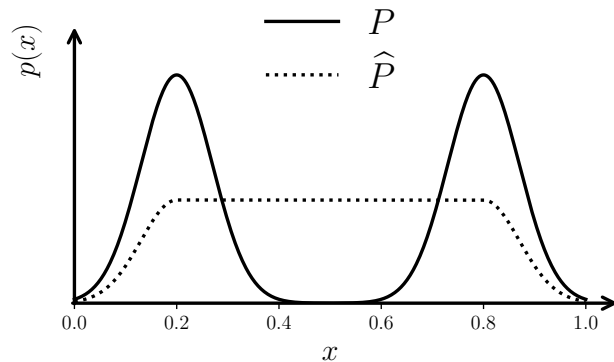
Improving:
How can we improve the
quality and diversity of a
pre-trained generative models?

SAMPLING FROM A GENERATIVE MODEL

GENERAL SETTING

To sample a point from the learned distribution \hat{P} :

- ▶ Sample $z \sim Q$.
- ▶ Compute $x = G(z)$.



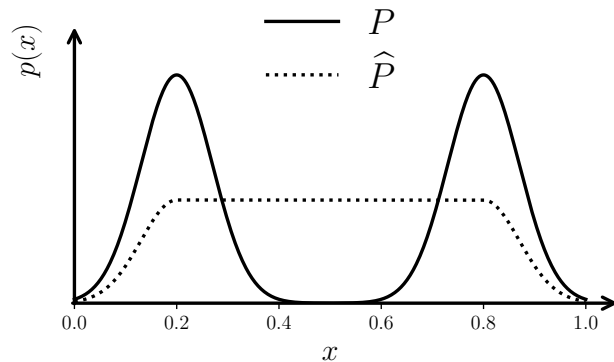
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$$P \neq \hat{P}$$



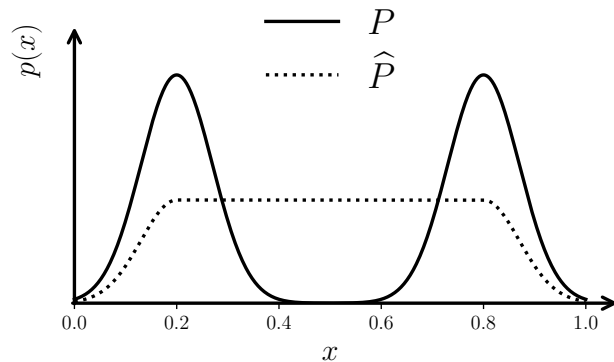
SAMPLING FROM A GENERATIVE MODEL

GENERAL SETTING

To sample a point from the learned distribution \hat{P} :

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- ▶ Compute $x = G(z)$.

We have an estimation of $\frac{p(x)}{\hat{p}(x)}$ using $\nabla f^*(T(x))$.



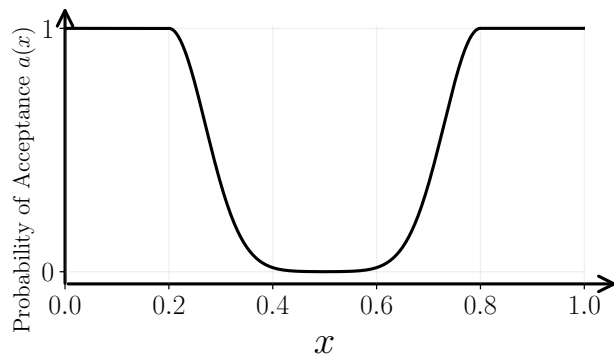
SAMPLING FROM A GENERATIVE MODEL

REJECTION SAMPLING

To sample a point from the refined distribution \tilde{P} :

- ▶ Sample $z \sim Q$.
- ▶ Compute $x = G(z)$.
- ▶ Accept x with probability $a(x)$.

Using $\frac{p(x)}{\tilde{p}(x)}$ in $a(x)$ allows sampling from P .



SAMPLING FROM A GENERATIVE MODEL

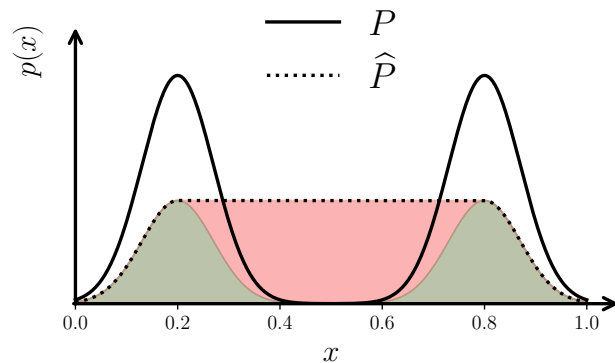
REJECTION SAMPLING

To sample a point from the refined distribution \tilde{P} :

- ▶ Sample $z \sim Q$.
- ▶ Compute $x = G(z)$.
- ▶ Accept x with probability $a(x)$.

The acceptance rate is :

$$\mathbb{E}_{\hat{P}}[a(x)].$$



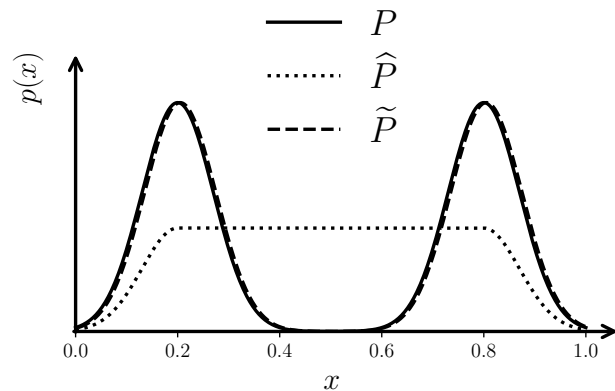
SAMPLING FROM A GENERATIVE MODEL

REJECTION SAMPLING

To sample a point from the refined distribution \tilde{P} :

- ▶ Sample $z \sim Q$.
- ▶ Compute $x = G(z)$.
- ▶ Accept x with probability $a(x)$.

It defines a new distribution \tilde{P} .



SAMPLING FROM A GENERATIVE MODEL

REJECTION SAMPLING IN HIGH DIMENSION

BUDGETED REJECTION SAMPLING

TUNING THE ACCEPTANCE RATE

Definition 3.1 (Discriminator Rejection Sampling (DRS) - Azadi et al. [2])

Let $\gamma \in \mathbb{R}$, the acceptance probability is:

$$a_{\text{DRS}}(\mathbf{x}) = \frac{r(\mathbf{x})}{r(\mathbf{x})(1 - e^\gamma) + Me^\gamma}.$$

If $\gamma < 0$, then the acceptance rate increases.

BUDGETED REJECTION SAMPLING

TUNING THE ACCEPTANCE RATE

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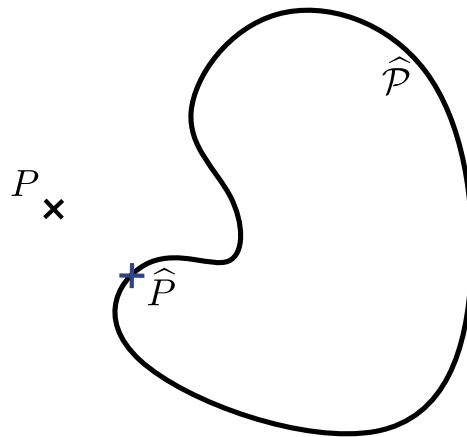
If $\gamma < 0$, then the acceptance rate increases.

OPTIMAL BUDGETED REJECTION SAMPLING

DEFINITION

Traditionally, the goal is:

$$\min_G \mathcal{D}_f(P \parallel \hat{P}_G)$$



Distribution Space

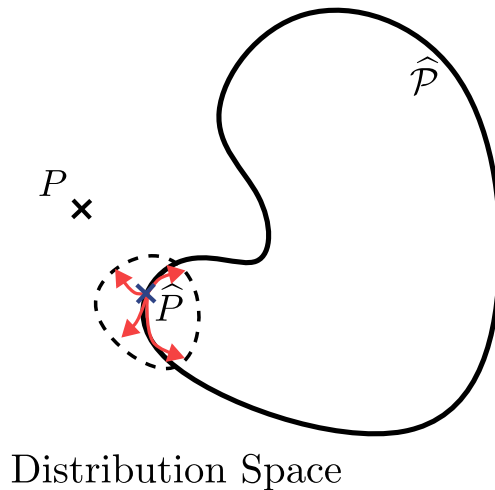
OPTIMAL BUDGETED REJECTION SAMPLING

DEFINITION

Traditionally, the goal is:

$$\min_G \mathcal{D}_f(P \parallel \hat{P}_G)$$

An acceptance function $a(x)$ such that the acceptance rate is greater than $1/K$ defines a refined distribution \tilde{P}_a in a convex set that contains \hat{P}_G .

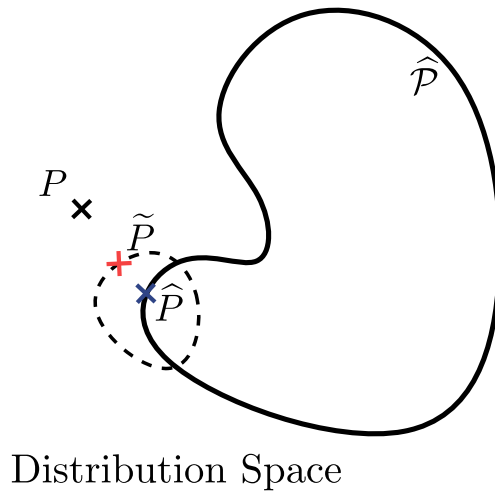


OPTIMAL BUDGETED REJECTION SAMPLING

DEFINITION

With a given \hat{P}_G , our goal is:

$$\begin{aligned} \min_a \quad & \mathcal{D}_f(P \parallel \tilde{P}_a) \\ \text{s.t.} \quad & \begin{cases} \mathbb{E}_{\hat{P}} [a(\mathbf{x})] \geq 1/K, \\ \forall \mathbf{x} \in \mathcal{X}, 0 \leq a(\mathbf{x}) \leq 1. \end{cases} \end{aligned} \quad (13)$$



OPTIMAL BUDGETED REJECTION SAMPLING

DEFINITION

Theorem 3.2 (Optimal Acceptance Function)

For a sampling budget $K \geq 1$ and finite \mathcal{X} , the solution is,

$$a_{\text{OBRS}}(\mathbf{x}) = \min \left(\frac{p(\mathbf{x}) c_K}{\hat{p}(\mathbf{x}) M}, 1 \right), \quad (14)$$

where $c_K \geq 1$ is such that $\mathbb{E}_{\mathbf{x} \sim \hat{p}}[a_{\text{OBRS}}(\mathbf{x})] = 1/K$.

OPTIMAL BUDGETED REJECTION SAMPLING

DEFINITION

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For a sampling budget $K \geq 1$ and finite \mathcal{X} , the solution is,

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where $c_K \geq 1$ is such that $\mathbb{E}_{\mathbf{x} \sim \widehat{p}}[a_{\text{OBRS}}(\mathbf{x})] = 1/K$.

IMPROVING PRECISION AND RECALL

EFFECT OF THE OBRS

Proposition 3.3 (Precision and Recall Improvement)

Let $K \leq M$ be the budget for the OBRS. For any $(\alpha, \beta) \in \text{PRD}(P, \hat{P})$ we have $(\alpha', \beta) \in \text{PRD}(P, \tilde{P}_{a_{\text{OBRS}}})$ with $\alpha' = \min \{1, K\alpha\}$.

IMPROVING PRECISION AND RECALL

EFFECT OF THE OBRS

Proposition 3.3 (Precision and Recall Improvement)

Let $K \leq M$ be the budget for the OBRS. For any $(\alpha, \beta) \in \text{PRD}(P, \hat{P})$ we have $(\alpha', \beta) \in \text{PRD}(P, \tilde{P}_{a_{\text{OBRS}}})$ with $\alpha' = \min\{1, K\alpha\}$.

IMPROVING PRECISION AND RECALL

EFFECT OF THE OBRS

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IMPROVING PRECISION AND RECALL

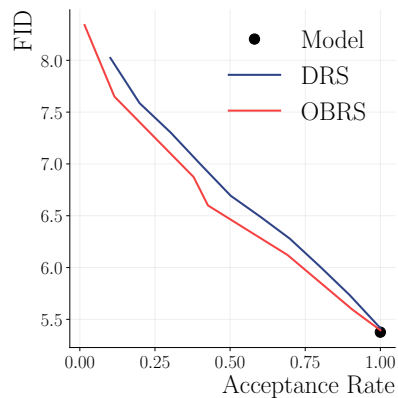
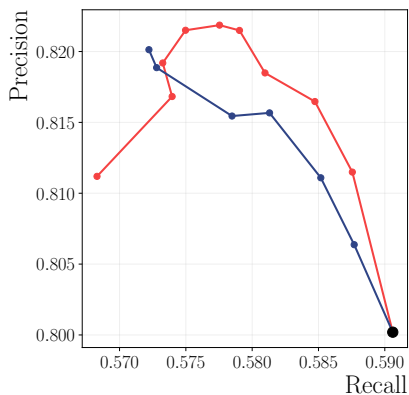
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IMPROVING PRECISION AND RECALL

IN PRACTICE



1/K	FID	P	R
0.25	1.57	78.48	86.73
0.50	1.58	78.23	86.05
0.75	1.77	77.94	86.54
1	1.97	77.91	86.62

GAN on CelebA

Diffusion Model on
CIFAR-10

OTHER METHODS TO IMPROVE PRECISION AND RECALL

BOOSTING

Boosting Generative models:

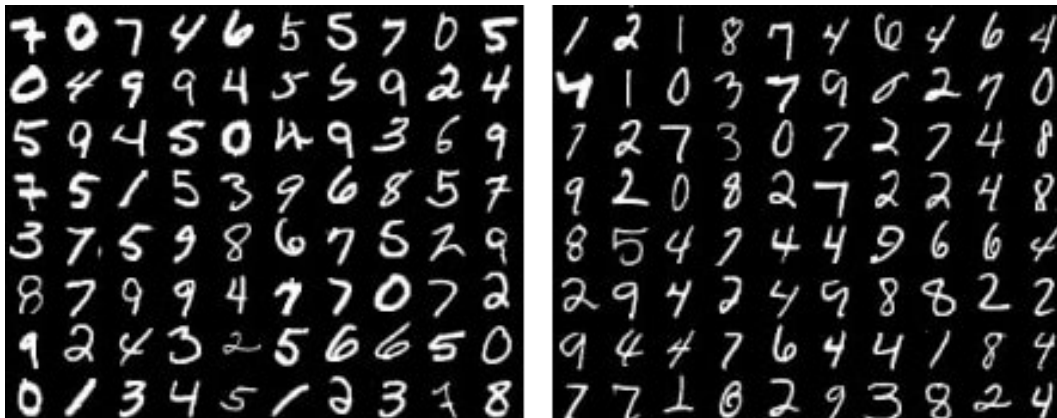


Figure. Left: Samples from the dataset given high weights by the discriminator. Right: Samples from the dataset given low weights by the discriminator. The next model will focus on the sample on the right. Source: Tolstikhin et al. [23]

- ▶ Tolstikhin et al. [23]
- ▶ Grover and Ermon [10]

OTHER METHODS TO IMPROVE PRECISION AND RECALL

GRADIENT ASCENT

Using the discriminator as a classifier and perform a gradient descent:

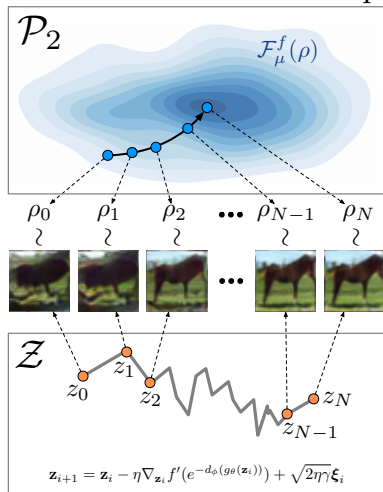


Figure. Source: Ansari et al. [1]

- ▶ Ansari et al. [1]
- ▶ Tanaka [22]
- ▶ Che et al. [7]

OTHER METHODS TO IMPROVE PRECISION AND RECALL

GAUSSIAN MIXTURES

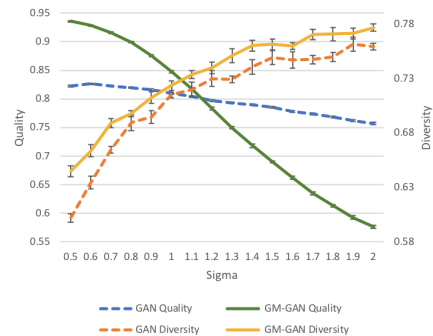
Training a Gaussian Mixture $\mathcal{N}(\mu_k, \sigma I)$ in the latent space:



(a) $\sigma = 0.1$

(b) $\sigma = 1$

(c) $\sigma = 2$



(d) Precision and Recall

Figure. Source: Ben-Yosef and Weinshall [3]

- ▶ Ben-Yosef and Weinshall [3]
- ▶ Pandeva and Schubert [18]
- ▶ Alternative idea: Use Expectation-Maximization Bishop [4]

RECAP

References to evaluate generative models:

- ▶ FID: Heusel et al. [11]
- ▶ PR-Curves: Sajjadi et al. [19]
- ▶ Support based metrics: Kynkäänniemi et al. [15]

Methods to tune precision and recall:

- ▶ Truncation: Karras et al. [13], Kingma and Dhariwal [14]
- ▶ f -GAN: Nowozin et al. [17]
- ▶ PR-GAN: Verine et al. [25]

RECAP

Methods to improve precision and recall:

- ▶ Rejecting samples: Azadi et al. [2], Verine et al. [25], Turner et al. [24], Tanaka [22]
- ▶ Boosting: Tolstikhin et al. [23], Grover and Ermon [10]
- ▶ Gradient Ascent: Ansari et al. [1], Tanaka [22], Che et al. [7]
- ▶ Latent Space Reshaping: Ben-Yosef and Weinshall [3], Pandeva and Schubert [18], Issenhuth et al. [12]
- ▶ EM in the latent space: Bishop [4]

CONCLUSION

Thanks !

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